DEPARTMENT OF AUTOMOBILE ENGINEERING ANNA UNIVERSITY, CHENNAI

VISION OF THE DEPARTMENT

"To be a premier department in Automobile Engineering and reach the highest academic level in the field of Automobile Engineering by imparting knowledge, continuously enhancing Research & Development activities, supporting industries through consultancy programme and providing the nation with high quality engineers"

MISSION OF THE DEPARTMENT

- 1. To prepare students **excel in their chosen professions** by offering **high quality education** in **automobile engineering** with fundamental knowledge, interdisciplinary problem-solving skills and **confidence** required.
- 2. To provide **supportive** and **diverse environment** that encourage students to achieve the **best of their abilities** to be **innovators** or **job providers**.
- 3. To maintain constant and active partnership with industries for technology development and transfer through consultancy projects.

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ANNA UNIVERSITY, CHENNAI UNIVERSITY DEPARTMENTS M.E. AUTOMOBILE ENGINEERING (R-2023) REGULATIONS 2023 CHOICE BASED CREDIT SYSTEM I TO IV SEMESTERS CURRICULA AND SYLLABI

1. PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

	Professional Excellence: Graduates will demonstrate expertise in the field of
I.	Automobile Engineering, applying advanced knowledge and skills to design, analyze, and optimize automotive systems and components. They will exhibit a strong understanding of industry practices, emerging technologies, and sustainable solutions.
	Leadership and Innovation: Graduates will exhibit leadership qualities, demonstrating
	the ability to effectively lead teams, manage projects, and drive innovation in the
II.	automotive industry. They will be capable of identifying and addressing complex
	engineering challenges, developing creative and sustainable solutions, and adapting to
	evolving technological advancements.
	Ethical and Social Responsibility: Graduates will uphold high ethical standards and
	exhibit a strong sense of social responsibility. They will prioritize safety, environmental
ш.	considerations, and ethical practices in the design, development, and operation of
	automobile systems. They will contribute to the betterment of society by addressing
	societal needs and advancing sustainable and responsible practices in the automotive
	field.

2. PROGRAMME OUTCOMES(POs):

PO	Programme Outcomes
1	An ability to independently carry out research/investigation and development work to solve practical problems
2	An ability to write and present a substantial technical report/document
3	Students should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program
4	Foster the preparedness of postgraduates at local, regional, and global levels to excel in various career paths, including government services, research and development organizations, corporate sectors, academic institutes, and industries.
5	Cultivate the ability of postgraduates to function effectively both as independent contributors and as team members within a multidisciplinary setting.
6	Nurture postgraduates to become engineering solution providers, addressing the nation's environmental, societal, and economic challenges.

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3. PEO/PO Mapping:

	POs									
PEO	1	2	3	4	5	6				
Ι.	3	3	3	3	3	3				
II.	3	3	3	3	3	3				
III.	3	3	3	3	3	3				

1,2,3, -, scale against the correlation PO's with PEO's

4. PROGRAM SPECIFIC OUTCOMES (PSOS):

- 1. Apply advanced engineering principles, state-of-the-art tools, and software to design, analyze, and optimize automotive systems and components.
- 2. Develop innovative and sustainable solutions to address complex challenges in the field of Automobile Engineering, considering safety, environmental, and ethical considerations.
- 3. Demonstrate effective communication, teamwork, and leadership skills while staying updated with the latest advancements in automobile technology, fostering a commitment to lifelong learning and professional development.



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PROGRAM ARTICULATION MATRIX

		Course Name	PO1	PO2	PO3	PO4	PO5	PO6	PSO1	PSO2	PSO3
		Advanced Numerical Methods	3	3	3	3	2	2	-	-	-
		Automotive Chassis	3	2	2	3	3	3	3	3	2
	~	Automotive Transmission	3	2	2	2	2	2	3	3	2
		Engine and Auxiliary Systems	3	3	3	3	3	3	3	3	2
	Sem	Vehicle Design cum Laboratory	3	3	3	3	3	3	3	3	2
		Research Methodology and IPR	3	3	2	-	-	-	-	-	-
RI		Engine and Chassis Components Laboratory	3	2	2	3	3	3	3	3	2
YEAR		Automotive Pollution and Control	3	3	3	3	3	3	3	3	2
X		Dynamics of Road Vehicles	3	3	3	3	3	3	3	3	2
	Sem 2	Vehicle Body Engineering and Ergonomics	3	2	2	2	2	2	3	3	2
		Vehicle Electrical and Electronics System cum Laboratory	3	3	3	3	3	3	3	3	2
		Vehicle Management Systems	3	3	3	3	3	3	3	3	2
		Engine and Vehicle Testing Laboratory	3	2	2	3	3	3	3	3	2
		Technical Seminar	3	3	3	3	3	3	3	3	3
	n 3	Electric and Hybrid Vehicles	3	3	3	3	3	3	3	3	2
AR II	Sem	Project Work I	3	3	3	3	3	3	3	3	3
YEAR	Sem 4	Project Work II		3	3	3	3	3	3	3	3

PROGRESS THROUGH KNOWLEDGE

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ANNA UNIVERSITY, CHENNAI M.E. AUTOMOBILE ENGINEERING REGULATIONS 2023 CHOICE BASED CREDIT SYSTEM I TO IV SEMESTER CURRICULUM AND SYLLABI SEMESTER I

SL.	COURSE	COURSE TITLE	CATEG	PEF	RIODS WEE	K	TOTAL CONTACT	CREDITS	
NO.	CODE		ORY	L	Т	Ρ	PERIODS	UNEDITO	
THEOF	۲Y								
1	MA3155	Advanced Numerical Methods	FC	4	0	0	4	4	
2	AM3101	Automotive Chassis	PCC	3	1	0	4	4	
3	AM3102	Automotive Transmission	PCC	3	0	0	3	3	
4	AM3103	Engine and Auxiliary Systems	PCC	3	0	0	3	3	
5	AM3104	Vehicle Design cum Laboratory	PCC	3	0	3	6	4.5	
6	RM3151	Research Methodology and IPR	RMC	2	1	0	3	3	
PRAC1	FICAL				5				
7	AM3111	Engine and Chassis Components Laboratory	PCC	0	0	3	3	1.5	
			TOTAL	18	2	6	26	23	

SEMESTER II

SL.	COURSE		CATE	PER	IODS WEI	PER EK	TOTAL CONTACT	
NO.	CODE	COURSE TITLE	GORY	L	Т	Ρ	PERIODS	CREDITS
THEOF	RY							
1.	AM3201	Automotive Pollution and Control	PCC	3	0	0	3	3
2.	AM3202	Dynamics of Road Vehicles	PCC	3	0	2	5	4
3.	AM3203	Vehicle Body Engineering and Ergonomics	PCC	3	0	0	3	3
4.	AM3204	Vehicle Electrical and Electronics System cum Laboratory	PCC	3	0	3	6	4.5
5.	AM3205	Vehicle Management Systems	PCC	3	0	0	3	3
6.		Professional Elective – I	PEC	3	0	0	3	3
PRACI	FICAL							
7	AM3211	Engine and Vehicle Testing Laboratory	PCC	0	0	3	3	1.5
8	AM3212	Technical Seminar	EEC	0	0	4	4	2
	•		TOTAL	18	0	12	30	24

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SEMESTER III

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY		PERIODS PER WEEK		PER WEEK		PER WEEK		PER WEEK		PER WEEK		PER WEEK		PER WEEK		TOTAL CONTACT PERIODS	CREDITS
				L T P		Ρ	FERIOD3													
1.	AM3351	Electric and Hybrid Vehicles	PCC	3	0	0	3	3												
2.		Professional Elective – II	PEC	3	0	0	3	3												
3.		Professional Elective – III	PEC	3	0	0	3	3												
4.		Professional Elective – IV	PEC	3	0	0	3	3												
PRAC	PRACTICAL																			
5.	AM3311	Project Work I	EEC	0 0 12		12	12	6												
			TOTAL	12	0	12	24	18												

SEMESTER IV

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY		RIC PEF / <u>EE</u> T		TOTAL CONTACT PERIODS	CREDITS
PRACT	ICAL			12				
1.	AM3411	Project Work II	EEC	0	0	24	24	12
		3. UN	TOTAL	0	0	24	24	12

TOTAL CREDITS TO BE EARNED FOR THE AWARD OF THE DEGREE = 77



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FOUNDATION COURSES (FC)

S.	COURSE		PERIC	DS PER V	VEEK		ermreter
NO CODE	COURSE TITLE	Lecture	Tutorial	Practical	CREDITS	SEMESTER	
1.	MA3155	Advanced Numerical Methods	4	0	0	4	I

PROFESSIONAL CORE COURSES (PCC)

S.	COURSE	COURSE TITLE	PERIC	DS PER	WEEK	CREDITS	SEMESTER
NO	CODE		Lecture	Tutorial	Practical	GREDITS	
1	AM3101	Automotive Chassis	3	1	0	4	I
2	AM3102	Automotive Transmission	3	0	0	3	I
3	AM3103	Engine and Auxiliary Systems	3	0	0	3	I
4	AM3104	Vehicle Design cum Laboratory	3	0	3	4.5	I
5	AM3111	Engine and Chassis Components Laboratory	0	0	3	1.5	I
6	AM3201	Automotive Pollution and Control	3	0	0	3	II
7	AM3202	Dynamics of Road Vehicles	3	0	2	4	П
8	AM3203	Vehicle Body Engineering and Ergonomics	3	0	0	3	II
9	AM3204	Vehicle Electrical and Electronics System cum Laboratory	3	0	3	4.5	II
10	AM3205	Vehicle Management Systems	3	0	0	3	II
11	AM3211	Engine and Vehicle Testing Laboratory	0	0	3	1.5	II
12	AM3351	Electric and Hybrid Vehicles	3	0	0	3	ш
L		PROGRESS THRO	JGH KN	OWLE	DGE		

RESEARCH METHODOLOGY AND IPR COURSES (RMC)

S.	COURSE	COURSE TITLE	PERI	ODS PER \	NEEK		SEMESTED	
NO	CODE	COURSE IIILE	Lecture	Tutorial	Practical	CREDITS	SEMESTER	
1.	RM3151	Research Methodology and IPR	2	1	0	3	I	

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PROFESSIONAL ELECTIVES (PEC)

S.No	Course Code	Course Title	Category		erio per Vee	•	Total Contact Periods	Credits
				L	Т	Ρ		
1	AM3001	Alternative Fuels and Propulsion Systems	PEC	3	0	0	3	3
2	AM3002	Automotive Aerodynamics	PEC	3	0	0	3	3
3	AM3003	Automotive Fault Diagnosis	PEC	3	0	0	3	3
4	AM3004	Automotive Instrumentation and Testing	PEC	3	0	0	3	3
5	AM3005	Automotive Materials	PEC	3	0	0	3	3
6	AM3006	Automotive Product Development	PEC	3	0	0	3	3
7	AM3007	Automotive Safety	PEC	3	0	0	3	3
8	AM3008	Autonomous and Connected Vehicles	PEC	3	0	0	3	3
9	AM3009	Design and Analysis of Experiments	PEC	3	0	0	3	3
10	AM3010	Engine Combustion Thermodynamics and Engine Heat Transfer	PEC	3	0	0	3	3
11	AM3011	Finite Element Methods in Automobile Engineering	PEC	3	0	0	3	3
12	AM3012	Hydraulic and Pneumatic Systems	PEC	3	0	0	3	3
13	AM3013	IC Engine Process Modelling	PEC	3	0	0	3	3
14	AM3014	Instrumentation and Experimental Techniques	PEC	3	0	0	3	3
15	AM3015	Intelligent Transport Systems	PEC	3	0	0	3	3
16	AM3016	Motorsport Technology	PEC	3	0	0	3	3
17	AM3017	Noise, Vibration and Harshness for Automobiles	PEC	3	0	0	3	3
18	AM3018	Production of Automotive Components	PEC	3	0	0	3	3
19	AM3019	Reverse Engineering in Automobile Engineering	PEC	2	0	2	4	3
20	AM3020	Special Purpose Vehicles	PEC	3	0	0	3	3
21	AM3021	Theory of Fuels and Lubricants	PEC	3	0	0	3	3
22	AM3022	Two and Three Wheelers	PEC	3	0	0	3	3
23	AM3023	Vehicle Air Conditioning Systems	PEC	3	0	0	3	3
24	AM3024	Vehicle Embedded Systems	PEC	3	0	0	3	3

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EMPLOYABILITY ENHANCEMENT COURSES (EEC)

			PERI	ODS PER	WEEK		
S. NO	COURSE CODE	COURSE TITLE	Lecture	Tutorial	Practical	CREDITS	SEMESTER
1.	AM3212	Technical Seminar	0	0	4	2	I
2.	AM3311	Project Work I	0	0	12	6	III
3.	AM3411	Project Work II	0	0	24	12	IV
				TOTAL C	REDITS	20	

SUMMARY

	N	I.E. AUTOMO	BILE ENGINE	ERING		
S.No	Subject Area		Credits			
		I	II	111	IV	Total
1	FC	4	0	0	0	4
2	PCC	16	19	3	0	38
3	PEC	0	3	9	0	12
4	RMC	3	0	0	0	3
5	EEC	0	2	6	12	20
	Total	23	24	18	12	77



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ADVANCED NUMERICAL METHODS

OBJECTIVES

- To make the students understand the methods/algorithms to numerically solve a system of simultaneous algebraic equations.
- To make the students understand the methods to numerically solve the system of simultaneous ordinary differential equations.
- To make the students understand the methods to numerically solve the partial differential equations.
- To make the students understand the methods to numerically solve the elliptic equations.
- To make the students understand the finite element methods for solving the PDEs.

UNIT I ALGEBRAIC EQUATIONS

Systems of linear equations: Gauss Elimination method, pivoting techniques, Thomas algorithm for tridiagonal system – Jacobi, Gauss Seidel, SOR iteration methods - Systems of nonlinear equations: Fixed point iterations, Newton Method, Eigenvalue problems: power method, Faddeev – Leverrier Method.

UNIT II ORDINARY DIFFERENTIAL EQUATIONS

Runge Kutta Methods for system of IVPs, numerical stability, Adams-Bashforth multistep method, solution of stiff ODEs, shooting method, BVP: Finite difference method, collocation method, orthogonal collocation method, Galerkin finite element method

UNIT III FINITE DIFFERENCE METHOD FOR TIME DEPENDENT PARTIAL DIFFERENTIAL EQUATION

Parabolic equations: explicit and implicit finite difference methods, weighted average approximation - Dirichlet and Neumann conditions – Two dimensional parabolic equations – ADI method; First order hyperbolic equations – method of characteristics, Lax-Wendroff explicit and implicit methods; numerical stability analysis, method of lines – Wave equation: Explicit scheme- Stability of above schemes

UNIT IV FINITE DIFFERENCE METHODS FOR ELLIPTIC EQUATIONS

Laplace and Poisson's equations in a rectangular region: Five point finite difference schemes, Leibmann's iterative methods, Dirichlet and Neumann conditions – Laplace equation in polar coordinates: finite difference schemes – approximation of derivatives near a curved boundary while using a square mesh.

UNIT V FINITE ELEMENT METHOD

Partial differential equations – Finite element method - collocation method, orthogonal collocation method, Galerkin finite element method.

PROGRESS THROUGH KNOWLEDGE

OUTCOMES:

At the end of the course, students will be able to

CO1 Solve numerically system of simultaneous algebraic equations.

CO2 Solve the simultaneous ordinary differential equations (IVP) numerically.

CO3 Solve numerically set of Partial differential equations.

CO4 Solve the set of Elliptic equations numerically.

CO5 Solve the set of PDEs by finite element method.

REFERENCES:

- 1. Burden. R. L. and Faires. J. D., "Numerical Analysis; Theory and Applications", India Edition, Cengage Learning, 2010.
- 2. Jain M.K., Iyengar S.R.K. and Jain R.K., Computational Methods for Partial Differential Equations, New Age International, 2nd Edition, New Delhi, 2016.
- 3. Morton K.W., and Mayers D.F., "Numerical Solution of Partial Differential Equations, Cambridge University Press, Second Edition, Cambridge, 2005.

Attested

TOTAL: 60 PERIODS

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L T P C 4 0 0 4

12

12

12

12

12

- 4. Santosh K Gupta, "Numerical Methods for Engineers", New Age International (P) Limited, Publishers, New Delhi, 2014.
- 5. Sastry S.S., "Introductory Methods of Numerical Analysis", Prentice Hall of India Pvt. Limited, 5th Edition, New Delhi, 2012.
- 6. Saumyen Guha and Rajesh Srivastava, "Numerical methods for Engineering and Science", Oxford Higher Education, New Delhi, 2010.

CO-PO Mapping:

COs			PC	Ds				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3	2	2	3	3	2
2	3	3	3	3	2	2	3	3	2
3	3	3	3	3	2	2	3	3	2
4	3	3	3	3	2	2	3	3	2
5	3	3	3	3	2	2	3	3	2
AVG	3	3	3	3	2	2	3	3	2



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AM31	01	AUTOMOTIVE CHASSIS	L	Т	Р	С
/	•		3	1	0	4
COLLE		ECTIVES:	v	•	v	
		tand the basic knowledge about various vehicle frames	fron	t avle	e eta	oorina
		nd understand the conditions for true rolling motion of who				
		ze the construction and working principle of drive line, fina				
	ystems			e anu	une	ential
		the knowledge about the constructional feature of rear ax		وامم	and t	Vres
		te the working principles of both conventional and ind				
	ystem.	te the working principles of both conventional and ind	epen		suspe	1131011
		strate working principle of braking system used in automo	hila			
0.	o acmon	strate working principle of braking system used in autome	one.			
UNIT		INTRODUCTION, FRAME, STEERING SYSTEM				12
		sis layout, with reference to Power Plant location and c	Irive	vario	is tvr	
		acting on vehicle frame, Constructional details and materi				
	•	es of Front Axles and Stub Axles, Front Wheel Geomet				•
		of Wheels during Steering, Ackerman's and Davis S				
		Curve, Steering Linkages, Different Types of Steering Ge				
		er-Steer, Reversible and Irreversible Steering, EPAS.		•	•	
UNIT		PROPELLER SHAFT AND FINAL DRIVE				12
Effect	of Drivin	g Thrust, torque reactions and side thrust, Hotchkiss dri	ive, to	orque	tube	drive,
radius	s rods ar	d stabilizers, Propeller Shaft, Universal Joints, Consta	ant Ve	elocity	/ Uni	versal
Joints	s, Front W	/heel drive, Final drive, different types, Double reduction	n and	twin	speed	d final
drives	s, Differen	tial principle and types, limited speed differential.				
UNIT		AXLES AND TYRES				12
		nd Design of Drive Axles, Types of Loads acting on drive				
		Floating and Semi-Floating Axles, Axle Housings an				
		Details of Different Types of Wheels and Rims, Differen	nt Typ	es of	Tyre	s and
their c	construction	onal details.				
	N7					10
UNIT		SUSPENSION SYSTEM				12
		pension System, Types of Suspension Springs, Cons				
		of Single Leaf, Multi-Leaf, Coil, Torsion bar, Rubber, Pr				
		sion Spring Systems, Independent Suspension Syste	m, re	elesco	pic :	5поск
Absor	bers.					
UNIT	V	BRAKING SYSTEM				12
		nobile Braking, Stopping Distance Time and Braking Effici	iencv.	Effec	t of V	
	•	Braking, Theory of Drum Brakes, Leading and Trailing S				•
		Details of Drum Brake and its Activators, Disc Brake				
		Hydraulic Braking System, Mechanical Braking System				
		-Assisted Braking System, Anti-Lock Braking System.	,	2.		3
			TOT	AL:45	PER	IODS

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COUR	RSE OUTCOMES:
CO1	Identify the different types of chassis layout, frames used in Automotive.
CO2	Appraise different types of drive line systems and steering system drives used in
	Automotive.
CO3	Acquire knowledge about different types of front axle and rear axles, wheel and tyre
	used in motor vehicles.
CO4	Expose to the working principle of conventional and independent suspension systems.
CO5	Analyse working principles of brake and its subsystems.
TEXT	BOOKS:
1.	Kirpal Singh, Automobile Engineering, Standard Publisher, New Delhi, 2017
2.	K.K.Ramalingam, "Automobile Engineering", scitech publication (India), 2011.
3.	R.K. Rajput, A Text-Book of Automobile Engineering, Laxmi Publications Private
	Limited, 2015
REFE	RENCES:
1.	Heinz Hazler, Modern Vehicle Technology, Butterworth, London, 2005.
2.	Heldt P.M., Automotive Chassis, Chilton Co., New York, 1990
2	Newton Steads and Correct Mater Vahiolog, 12th Edition, Butterworth, London, 2005

3. Newton Steeds and Garret, Motor Vehicles, 13th Edition, Butterworth, London, 2005.

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- 4. N.K. Giri, Automotive Mechanics, Kanna Publishers, 2007
- 5. William. H. Crows Work shop Manuel 2005

		1.						
		P	Os				PSOs	
1	2	3	4	5	6	1	2	3
3	2	2	3	3	3	3	3	2
3	2	2	3	3	3	3	3	2
3	2	2	3	3	3	3	3	2
3	2	2	3	3	3	3	3	2
3	2	2	3	3	3	3	3	2
3	2	2	3	3	3	3	3	2
	1 3 3 3 3 3 3 3 3 3 3	3 2 3 2 3 2 3 2 3 2 3 2 3 2	1 2 3 3 2 2 3 2 2 3 2 2 3 2 2 3 2 2 3 2 2 3 2 2 3 2 2 3 2 2	3 2 2 3 3 2 2 3 3 2 2 3 3 2 2 3 3 2 2 3 3 2 2 3	12345322333223332233322333223332233	123456322333322333322333322333322333322333	1 2 3 4 5 6 1 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3 3 2 2 3 3 3 3 3	1234561232233333322333333223333332233333322333333223333332233333

PROGRESS THROUGH KNOWLEDGE

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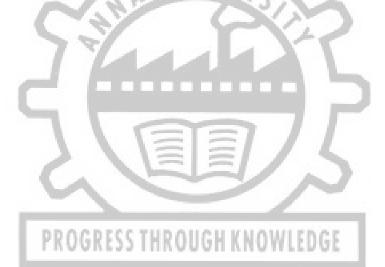
AM31	02	AUTOMOTIVE TRANSMISSION	Т	Ρ	С
		3	0	0	3
		JECTIVES: The objective of this course is to prepare the			
	Ŭ	the construction and principle of mechanical transmission cor	mponer	nts like	e
1. 2.	Clutch Gear Bo				
<u>2.</u> 3.		namic devices			
<u>4.</u>		atic devices			
5.		tic transmission system, Electric drive used in road vehicles.			
UNIT	1	CLUTCH			9
– Fun	nctions-Ty	f transmission system, Types of transmission system, Requir pes of clutches, construction and operation of Single plate ing clutches. Centrifugal clutch, DCT, Electronic clutch.			
UNIT	11	GEAR BOX			9
gear l examp	boxes, Au ples on p	ar box. Construction and working principle of sliding, constant atomatic manual transmission. Introduction to epicycle gear erformance of automobile such as Resistance to motion, Trad and acceleration. Determination of gear ratios for different ve	trains, ctive eff	Num fort, E	nerica Ingine
UNIT		HYDRODYNAMIC TRANSMISSION			9
		tion of drag torque. Torque converter - principles - Performan	limitati nce cha		
– adva UNIT	antages - IV	- limitations – multistage and polyphase torque converters.	nce cha	aracte	ristic:
– adva UNIT Hydro Advar	antages - IV ostatic driv	- limitations – multistage and polyphase torque converters.	nce cha	aracte ive sy	ristics
– adva UNIT Hydro Advar constr UNIT	antages - IV ostatic driv ntages a ruction ar V	 limitations – multistage and polyphase torque converters. HYDROSTATIC DRIVE re; various types of hydrostatic systems – Principles of Hydrostatic dimitations. Comparison of hydrostatic drive with hydrostatic drive of typical Janny hydrostatic drive. AUTOMATIC TRANSMISSION AND ELECTRIC DRIVE 	nce cha static dr drodyna	ive sy	ristics 9 stem drive 9
– adva UNIT Hydro Advar constr UNIT Wilsor longitu transn types-	antages - IV pstatic drivent ntages and ruction ar V n gear boom udinally resion. Control - Principle	 limitations – multistage and polyphase torque converters. HYDROSTATIC DRIVE re; various types of hydrostatic systems – Principles of Hydrostatic drive with hydrostatic drive with hydrostatic drive with hydrostatic drive. AUTOMATIC TRANSMISSION AND ELECTRIC DRIVE re- Cotal electric transmission. Chevrolet "Turboglide" transmission unted automatic transmission - Hydraulic control system continuously Variable Transmission (CVT) — types – Operation of early and modified Ward Leonard Control System-Advan 	static dr drodyna sion. – ems of ons. Ele	ive sy amic Fours auto ectric	ristic 9 stem drive 9 speed omatio drive
– adva UNIT Hydro Advar constr UNIT Wilsor ongitu ransn sypes-	antages - IV pstatic drivent ntages and ruction ar V n gear boom udinally resion. Control - Principle	 limitations – multistage and polyphase torque converters. HYDROSTATIC DRIVE re; various types of hydrostatic systems – Principles of Hydrostatic drive with hydrostatic of typical Janny hydrostatic drive. AUTOMATIC TRANSMISSION AND ELECTRIC DRIVE x- Cotal electric transmission. Chevrolet "Turboglide" transmission unted automatic transmission - Hydraulic control system of early and modified Ward Leonard Control System-Advananual Transmission (AMT) - Modern electric drives. 	static dr drodyna sion. – ems of ons. Ele	Fours amic Fours auto ectric	ristic: g stem drive speedomation drive ation
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- 2. Heldt, P.M., "Torque converters", Chilton Book Co., 1962.
- 3. Iqbal Husain, "Electric and Hybrid Vehicles Design Fundamentals", CRC PRESS Boca Raton London New York Washington, D.C.

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AM 3	103	ENGINE AND AUXILLARY SYSTEMS	L	Т	Ρ	С
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		ECTIVES:				
1.		art knowledge on basics of automotive SI and CI engines ction, working	s con	sisting	of ty	pes,
2.		erstand the engine induction and ignition and its functional re	quire	ments		
3.		the properties of gasoline and diesel fuel and combustion				d in
	diesel e		1 -			
4.	To imp	art the knowledge on engine cooling and lubrication r and the requirements of supercharger and turbocharger	equir	ement	s also	o to
5.		yze the performance characteristics of SI and CI engin	e and	d lear	n mo	dern
		ments in IC engine				
UNIT		ENGINE BASIC THEORY				ç
Introd	duction - E	ngine types – Operating cycle - Otto, diesel, dual operating o	cvcles	s – Fue	el air c	vcle
		les Two and four stroke engines - Engine design and or				
		nance and pollution curves for automobile engines – Rotary				
cycles	•		U			
UNIT		FUEL SUPPLY AND IGNITION SYSTEMS				9
Objec	ctive and t	heory of carburetion - carburetors, Types, Additional system	n and	mode	rn dev	ices
		- Calculation of air fuel ratio of carburetor - Diesel fuel injection				
- pum	nps and ii	njectors, Introduction to Petrol Injection system - convention	onal i	gnition	syste	ems
	Nce mech	anisms - Electronic Ignition - Problems on carburetor and di		•		
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V DIRECTOR Centre for Academic Courses Anna University, Chennai-600 025

CO5	Analys and Evaluate engine performance and exposed to gain knowledge on recent
	developments of prime sources
техт	BOOKS:
	1. John B.Heywood , "Internal Combustion Engines" , McGraw-Hill Book Company,
	ISBN No: 0-07-100499-8
	2. M.L. Mathur and R.P.Sharma, Internal Combustion Engine, Dhanpath Rai
	Publications (P) Ltd, New Delhi 110002
	3. V. Ganesan, Internal Combustion Engines, Tata-McGraw Hill Publishing Co., New
	Delhi,
REFE	ERENCES:
	1. Heinz Hesiler, Advanced engine technology. Butterworth Heinmann publications
	2. Heldt, P.M., High Speed Combustion Engines, Oxford IBH Publishing Co., Calcutta,
	3. K. K. Ramalingm, internal Combustion Engines, Scitech publications, Chennai, 2003.
	A Malagy VM Dissel Engine Operation and Maintenance McCraw Hill 1074

- 4. Maleev, V.M., Diesel Engine Operation and Maintenance, McGraw Hill, 1974.
- 5. Obert, E.F., Internal Combustion Engine analysis and Practice, International Text Book Co., Scranton, Pennsylvania, 1988.

COs			P	Os				PSOs	
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1	3	3	3	3	3	3	3	3	2
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4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2

PROGRESS THROUGH KNOWLEDGE

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	04	VEHICLE DESIGN CUM LABORATORY	L	Т	Р	С
			3	0	3	4.5
		(Use of Design Data Book is permitted)				
		JECTIVES:				
1.		derstand the various steps involved in the design of automotiv	e con	npone	nts	
2.		we their knowledge in designing engine components.		:		
3.		nplete design exercise and arrive at important dimensions of o	cnass	is con	npone	nts.
4. 5.		rn the use of standard practices in design. ermine the dimensions of front and rear axles				
J.	TOUEL					
UNIT	1	DESIGN OF CYLINDER, PISTON AND CONNECTING R	OD			18
		terial for cylinder and piston, design of cylinder, design of pi				
•	•	on assembly. Material for connecting rod, design of connecti n for car	ng roo	d asse	embly	Case
Sludy						
UNIT		DESIGN OF CRANK SHAFT AND VALVES				18
		rankshaft, design of crankshaft under bending and twisting.	Desigi	n - inle	et & e	xhaus
valves	s, tappe	ts. Design of cam & camshaft. Design of rocker arm.				
UNIT		DESIGN OF CLUTCHES AND GEARS				18
		gle plate clutch, multiplate clutch and cone clutch assemble	JV T	oraue	cana	
		n of clutch components. Gear train calculations, layout of ge				
		and selection of bearings. Design of three speed and four sp				
			,	9		
UNIT	IV	DESIGN OF VEHICLE FRAME AND SUSPENSION				18
	of load	ds-moments and stresses on frame members. Design Of				enger
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	SE OUTCOMES:
	udents will be able to
	Analyze the stress and strain imparted on automotive components
	Compute the design and find the dimension of the vehicle components.
CO3	Identify optimal design solutions to real-world problems in compliance with industry standards.
CO4	Demonstrate the design skill by creating new design strategy with the application of the knowledge.
CO5	Interpret the modern system in vehicle and would help in developing the system with less impact to the environment.
	BOOKS:
1.	Genta, Lorenzo Morello, "The Automotive Chassis Volume 1, Components Design", Springer International Edition.2014
2.	Khurmi. R.S. & Gupta. J.K., "A text book of Machine Design", Eurasia Publishing House (Pvt) Ltd, 2001.
3.	Stokes, "Manual gearbox design", Butterworth-Heinemann 1992
REFE	RENCES:
1.	"Design Data Hand Book", PSG College of Technology, 2013- Coimbatore.
2.	Dean Averns, "Automobile Chassis Design", Illife Book Co., 2001.
	Kolchin-Demidov, "Design of Automotive Engines"-Mir Publishers (1984)
4.	Lukin P G and Rodionov V, "Automobile Chassis Design and Calculations", Mir Publishers, Moscow, 1989.
5.	Robert C. Juvinall and Kurt M. Marshek, "Fundamentals of Machine component Design",6th Edition, Wiley, 2017

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3 -	3	3	3	3	2
2	3	3	3	3 =	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	PD 3CD	3	3.1	3	3	3	2

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RM3151

RESEARCH METHODOLOGY AND IPR

OBJECTIVES:

To impart knowledge on

- Formulation of research problems, design of experiment, collection of data, interpretation and presentation of result
- Intellectual property rights, patenting and licensing

UNIT I **RESEARCH PROBLEM FORMULATION**

Objectives of research, types of research, research process, approaches to research; conducting literature review- information sources, information retrieval, tools for identifying literature, Indexing and abstracting services, Citation indexes, summarizing the review, critical review, identifying research gap, conceptualizing and hypothesizing the research gap

RESEARCH DESIGN AND DATA COLLECTION UNIT II

Statistical design of experiments- types and principles; data types & classification; data collection methods and tools

UNIT III DATA ANALYSIS. INTERPRETATION AND REPORTING

Sampling, sampling error, measures of central tendency and variation,; test of hypothesis- concepts; data presentation- types of tables and illustrations: guidelines for writing the abstract, introduction. methodology, results and discussion, conclusion sections of a manuscript; guidelines for writing thesis, research proposal; References – Styles and methods, Citation and listing system of documents; plagiarism, ethical considerations in research

INTELLECTUAL PROPERTY RIGHTS **UNIT IV**

IPR, types of IPR - Patent, Designs, Trademarks and Trade secrets, Geographical indications, Copy rights, applicability of these IPR; , IPR & biodiversity; IPR development process, role of WIPO and WTO in IPR establishments, common rules of IPR practices, types and features of IPR agreement, functions of **UNESCO** in IPR maintenance.

UNIT V PATENTS

objectives and benefits of patent, concept, features of patent, inventive steps, specifications, types of patent application; patenting process - patent filling, examination of patent, grant of patent, revocation; equitable assignments; Licenses, licensing of patents; patent agents, registration of patent agents. **TOTAL: 45 PERIODS**

COURSE OUTCOMES

Upon completion of the course, the student can

- CO1: Describe different types of research; identify, review and define the research problem
- CO2: Select suitable design of experiment s; describe types of data and the tools for collection of data
- CO3: Explain the process of data analysis; interpret and present the result in suitable form
- CO4: Explain about Intellectual property rights, types and procedures

CO5: Execute patent filing and licensing

REFERENCES:

- 1. Cooper Donald R, Schindler Pamela S and Sharma JK, "Business Research Methods", Tata McGraw Hill Education, 11e (2012).
- 2. Soumitro Banerjee, "Research methodology for natural sciences", IISc Press, Kolkata, 2022,
- 3. Catherine J. Holland, "Intellectual property: Patents, Trademarks, Copyrights, Trade Secrets", Entrepreneur Press, 2007.
- 4. David Hunt, Long Nguyen, Matthew Rodgers, "Patent searching: tools & techniques", Wiley, 2007.
- 5. The Institute of Company Secretaries of India, Statutory body under an Act of parliament, "Professional Programme Intellectual Property Rights, Law and practice", September 2013.

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AM3111

ENGINE AND CHASSIS COMPONENTS LABORATORY

L	т	Ρ	С
0	0	3	1.5

COURSE OBJECTIVES:

- **1.** To assemble and disassemble the parts of an IC engine.
- **2.** To identify the various component of an IC engine.
- 3. To identify the various components in the transmission systems of an automobile.
- 4. To assemble and disassemble the various components of transmission system.
- 5. To study all the functions of automobile components

LIST OF EXPERIMENTS

- 1. To assemble and dismantle the Bus engine
- 2. To assemble and dismantle the V8 engine
- 3. To assemble and dismantle the CRDI engine
- 4. To assemble and dismantle the MPFI engine
- 5. To assemble and dismantle a Single plate, Diaphragm Clutch.
- 6. To assemble and dismantle a Constant-mesh, Sliding mesh gearbox
- 7. To assemble and dismantle the Transfer case
- 8. To assemble and dismantle the Differential, Rear axle
- 9. To assemble and dismantle the Front axle. Constant Velocity Joint.
- 10. To Study different chassis layouts
- 11. To Study the braking system
- 12. To Study the Suspension system

TOTAL:45 PERIODS

COURSE OUTCOMES:

- **CO1** Dismantle and Assemble the Engine components
- CO2 Identify & differentiate components of the Clutch and Gearbox,
- CO3 Understand the working of braking, Breaking and Suspension systems.
- CO4 Develop skills in Dismantling and assembling chassis components.
- CO5 Dismantle and Assemble axles differential.

PROGRESS THROUGH KNOWLEDGE

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	3	3	3	3	3	2
2	3	2	2	3	3	3	3	3	2
3	3	2	2	3	3	3	3	3	2
4	3	2	2	3	3	3	3	3	2
5	3	2	2	3	3	3	3	3	2
AVG	3	2	2	3	3	3	3	3	2

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AM3201 AUTOMOTIVE POLLUTION AND CONTROL L T P 3 0 0

COURSE OBJECTIVES:

- 1. To discuss the harmful effects of major pollutants on living beings and the environment
- 2. To analyze the formation of major pollutants like UBHC, CO, NOx, particulate matter and smoke.
- 3. To design various control techniques to reduce pollutants in combustion
- 4. To determine the various after treatment process to minimize emissions
- **5.** To demonstrate the various devices used to measure pollutants and discuss the Emission standards followed in various nations

UNIT I EMISSION FROM AUTOMOBILES

Sources of Pollution, Various emissions from Automobiles — Formation — Effects of pollutants on environment and human health – Evaluation of emission standards. Lubricants handling and harmful discharges. Introduction to CO2 emission, Carbon capturing, Introduction to Electro Magnetic Emissions, and Functional Safety of emission control devices.

UNIT II EMISSION FROM SPARK IGNITION ENGINE AND ITS 9 CONTROL

Emission formation in SI Engines- Carbon monoxide- Unburned hydrocarbon, NOx, Smoke Aldehyde emissions - Effects of design and operating variables on emission formation – controlling of pollutants - Catalytic converters, types of substrate and catalyst, Low temperature catalyst and activation— Charcoal Canister — Positive Crank case ventilation system, Secondary air injection, Thermal reactor, Laser Assisted Combustion. CO₂ control Techniques, Pre, Post and Oxy fuel combustion, Absorption, Adsorption and membrane separation.

UNIT III EMISSION FROM COMPRESSION IGNITION ENGINE AND ITS 9 CONTROL

Formation of White, Blue, and Black Smokes, NOx, soot, Sulphur particulate and Intermediate Compounds – Physical and Chemical delay — Significance Effect of Operating variables on Emission formation — Fumigation, EGR, HCCI, Turbo charger, Particulate Traps, Regeneration methods, SCR — Cetane number Effect.

UNIT IV NOISE POLLUTION FROM AUTOMOBILES

Sources of Noise — Engine Noise, Transmission Noise, vehicle structural Noise, aerodynamics noise, Exhaust Noise. Noise reduction in Automobiles — Encapsulation technique for noise reduction — Silencer Design.

UNIT V TEST PROCEDURES AND EMISSION MEASUREMENTS

Constant Volume Sampling I and 3 (CVSI &CVS3) Systems- Sampling Procedures — Chassis dyno – Transient dyno, Seven mode and thirteen mode cycles for Emission Sampling — Sampling problems — Emission analyzers —NDIR, FID, Chemiluminesecent, Smoke meters, Dilution Tunnel for PM measurement and Laser scattering method for PN measurement, SHED Test, Sound level meters. Homologation, EMC/EMI testing of Electric electronic devices. Onboard pollution measurement equipment's (PEMS). Emission regulations for off-road vehicles, TREM norms.

COURSE OUTCOMES:

- CO1 Differentiate the various emissions formed in IC engines
- **CO2** Analyze the effects of pollution on human health and environment
- **CO3** Design the control techniques for minimizing emissions
- **CO4** Identify suitable methods to reduce the noise emissions.
- **CO5** Categorize the emission norms

45 PERIODS

TOTAL:

С

3

9

9

9

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TEXT BOOKS:

- 1. B.P Pundir , Engine Emissions, Narosa publications 2nd edition 2017
- 2. D.J.Patterson and N.A.Henin, 'Emission from Combustion Engine and their control', Anna Arbor Science Publication,1985.
- 3. G.P.Springer and D.J.Patterson, Engine Emissions, Pollutant formation, Plenum Press, New York, 1986.

COs			PC	Ds				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3	3	3	3	3	2
2	3	3	3	3	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2



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AM32	202	DYNAMICS OF ROAD VEHICLES	L	Т	Ρ	С
			3	0	2	4
COUF	RSE OBJ	ECTIVES:				
1.	To prov	de fundamental knowledge of the vibration,				
2.		rt knowledge on tyres				
3.	To prov	de basic concepts on suspension design and function, rid	de mo	odes		
4.		uate the performance, longitudinal dynamics and control i		autom	obile	
5.	To provi	de basic analysis on handling, cornering stability and cor	ntrol			
UNIT		CONCEPT OF VIBRATION				15
Defini Formu Magn	itions, Ty ulation of ification	Simulation, Global and Vehicle Coordinate System. Fur pes, Free, Forced, Undamped and Damped Vibratic Governing equation. Response Analysis of Single DOF factor, Transmissibility ratio, Base excitation. Vibrati ruments, Torsional vibration, Critical speed.	n. V , Tw	ibratio o DOF	n anal ⁻ , Multi	ysis – DOF.
UNIT	11	TYRES				15
longite and c	udinal slip cornering	ngitudinal slip and slip angle concept, Relation betwo, Friction circle. Longitudinal and Lateral force at vario property of tire. Camber and camber trust. Performan f tyres. Various test carried on a tyre. Tyre models	us s	lip an	gles, 7	ractive
UNIT		VERTICAL DYNAMICS				15
Active Influe	e suspen nce of s	entation. MR & ER Dampers. Design and analysis of sion using Quarter car, Bicycle Model, Half car and suspension stiffness, suspension damping, and tire timization techniques. Air suspension system and their pr	full c stiff	ar vib ness.	rating	model.
UNIT	IV	LONGITUDINAL DYNAMICS AND CONTROL	-			15
force whee drive locati on sl	supplied eler. Calc vehicles ion. Long lope. Driv	forces and moments. Forces acting on a vehicle – Re by power plant. Equation of motion. Load distribution fo ulation of maximum acceleration, tractive effort and rea . Power limited acceleration and traction limited acceler itudinal load transfer during acceleration and braking. S eline dynamics. Braking and Driving torque. Prediction control, Traction control.	r thre actior eratio tabilit	ee-whe force on. Est ty of ve	eler and s for contraction for a for a contraction of the second	nd four- lifferent n of CG resting
UNIT	V	LATERAL DYNAMICS				15
Steeri input handl vehicl	ing Geon – Yaw ing chara le on bar	hetry – Steady state handling characteristics. Steady st velocity gain, Lateral acceleration gain, curvature res acteristics. Transient response characteristics. Direction ked road, during turn. Effect of suspension on corner s, effect of roll on vehicle dynamics. Yaw control. Stability	spons nal s ring.	se ga stabilit Roll d	in. Tes y. Stat	steering sting of pility of
Simul 1.	Single a	analysis of and Multi-Degree of Freedom System dinal and lateral forces of tires using Magic Formula Tire	mod	el	Atte	sted

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- 3. Passive Suspension System using Quarter / Half / Full Car model
- 4. Active Suspension System Control Strategy (PID, Skyhook, LQR) using Quarter / Half / Full Car model
- 5. Power requirement for a Vehicle
- 6. Double lane change maneuver
- 7. Mini-Project

TOTAL: 75 PERIODS

COURSE OUTCOMES:

At the end of the courses, the students can able to

- **CO1** Develop physical and mathematical models of a mechanical vibrating system
- **CO2** Indicate the forces and moment acting on tyres
- **CO3** Identify the suspension parameters that governs ride comfort
- **CO4** Evaluate the vehicle performance in longitudinal direction
- **CO5** Evaluate the lateral dynamics and control in an automobile

TEXT BOOKS:

- 1. Singiresu S. Rao, "Mechanical Vibrations SI Edition," Sixth Edition, Pearson, 2018
- 2. J. Y. Wong, "Theory of Ground Vehicles", Fifth Edition, Wiley-Interscience, 2022
- 3. Rajesh Rajamani, "Vehicle Dynamics and Control," Second edition, Springer, 2012
- 4. Reza N. Jazar, "Vehicle Dynamics: Theory and Application", Third edition, Springer, 2017

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- Dean Karnopp, "Vehicle Dynamics, Stability, and Control", Second Edition, CRC Press, 2013
- Michael Blundell & Damian Harty, "The Multibody Systems Approach to Vehicle Dynamics", 2nd Edition, Butterworth - Heinemann, 2014
- 4. Hans B Pacejka, "Tyre and Vehicle Dynamics," Second edition, Butterworth Heinemann, 2006

			A		Concerning of the second se				
COs			PC	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3	3	3	3	3	2
2	3	3	3	3	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2

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	203	VEHICLE BODY ENGINEERING AND ERGONOMICS	L	T	Ρ	С
<u></u>			3	0	0	3
<u>1.</u>		he knowledge on Car body				
2.	Bus boo					
<u>3.</u> 4.		rcial vehicle				
4. 5.	Ergono	aerodynamics				
5.	Ergono	TICS				
UNIT	1	CAR BODY DETAILS				9
oody visibi	terminolo ility. Drive rials. Safe	ody - Saloon, convertibles, Limousine, Estate Van, Racing gy - Visibility- regulations, driver's visibility, improvement in r seat design -Car Body Construction - Various panels aty: Safety design, safety equipment for cars – body correct	i visik in ca	oility a r bod	nd tes ies –	sts fo body
UNIT	- 11	BUS BODY DETAILS				9
Type body	s of bus l lay out, f	oody: based on capacity, distance travelled and based or oor height, engine location, entrance and exit location. Ty tions – Constructional details: Conventional and integral.				- Bus
UNIT						9
-		COMMERCIAL VEHICLE DETAILS nercial vehicle bodies - Light commercial vehicle body. C				-
UNIT						
Obje mom minir	ctives, Ve ents. Side num drag	VEHICLE AERODYNAMICS hicle drag and types. Various types of forces and moments wind effects on forces and moments. Various body optim Wind tunnels – Principle of operation, Types. Wind tunnel	izatio testi	on tecl ng suo	hniqu ch as:	s and es foi Flow
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Obje mom minir visua mom UNIT Introd Desie of Vie COU Upor CO1 CO2 CO3 CO4 CO5 TEX 1.Die 2. Ja	ctives, Ve lents. Side num drag alization tr lents by us V duction to gning Veh ew - stylin N Completi Differer Bus boo Comme Role of body de Ergono TBOOKS	hicle drag and types. Various types of forces and moments e wind effects on forces and moments. Various body optim Wind tunnels – Principle of operation, Types. Wind tunnel echniques, Airflow management test – measurement of sing wind tunnel balance. ERGONOMICS • Automotive Ergonomics, Ergonomics in Vehicle Designicles, Occupant Package, Controls and Displays Interface g in automotive design. COMES: on of the course, students will acquire knowledge on t aspects of car body, dy ercial vehicle bodies. various aerodynamic forces and moments, measuring in esign mics n., "The passenger car body", SAE International, 2000 ffy, "Body Repair Technology for 4-Wheelers", Cengage L	izatic testi f var jn, A - Intr T(on tech ng sud ious nthro oduct DTAL	hniqu ch as: forces pome ion to :	s anc es foi Flow s anc 9 try ir Field 45

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REFERENCES:

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- 2. Giles, G.J., "Body construction and design", Iliffe Books Ltd. Butterworth & Co., 1991.
- 3. John Fenton, "Vehicle Body layout and analysis", Mechanical Engg. Publication Ltd., London,1992.
- 4. Vivek D. Bhise," Ergonomics in The Automotive Design Process", CRS Press, 2016

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
2	3	2	2	2	2	2	3	3	2
3	3	2	2	2	2	2	3	3	2
4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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AM3	204	VEHICLE ELECTRICAL AND ELECTRONICS SYSTEM CUM LABORATORY	L	Т	Ρ	С
			3	0	3	4.5
		JECTIVES:				
1.	alterna	lerstand the need for different electrical circuits, starter batteri or in the vehicle.				
2.		exposure and understand the need for power electronics device	es, co	ontro	olled re	ectifier
		age controllers and choppers in automobile applications				
<u>3.</u>		w on ignition, lighting and auxiliary system used in modern vehic	les			
<u>4.</u>		common types of sensor and actuators used in vehicles.				al dan ar di
5.	vehicle	lerstand and differentiate the conventional and modern archi s	necu	ire	netwoi	rking
UNIT	- I	FUNDAMENTALS OF ELECTRICAL CIRCUITS, BATTERY, CHARGING SYSTEMS	STA	RTI	NG A	ND 1
D.C f	fundamer	tals: ohm's law, KVL & KCL law, AC Fundamentals: Analysis of si	imple	RC	, RL a	nd RL
		rallel circuits and phasor diagrams. Lead acid battery: - Desig			-	
chara	acteristics	, ratings and testing. Alternators: - Generation of electrical e	energ	gy ir	n the	vehicle
		details and Operating Principle, Voltage regulation, Ov				
		curve- Alternator circuits and designs. Starter Motors: - Overvie				
		ed drive Starter Types of starter motor- starter motor design -	- Sta	rter	motor	desig
varia	tions – st	arter motor control and power circuits				
UNIT		INDUCTION MOTOR & DRIVES				1
		and principle of operation - torque and torque-slip characteristics-	Effici	one	/_ Ann	
		ds – speed control drives of induction motor.	EIIICI	enc	y- App	licatio
UNIT	· III	POWER ELECTRONICS AND CONVERTORS				1
Powe	er diodes	and its characteristics - BJT, MOSFET, IGBT, SCR- Controlled Re	ctifie	ers a	nd AC	voltag
Cont	rollers, D	C to DC Converters- Buck, Boost, Buck-Boost converters, Inve	rters	- vo	ltage,	currer
resor	nant					
		TRANSDUCERS AND SIGNAL CONDITIONING			- (1
		naracteristics and classification, variable resistance-based trans				
		ermometer, Thermistor, hot-wire anemometer, piezo-resist sed transducers- LVDT, Induction potentiometer, Capacitive transmitter transmitter and the set of				
		sor, Proximity sensor- Piezoelectric transducer – Hall Effect tr				
		sensors, DAC and ADC principle, ADC IC's	anse	1000	a aut	omouv
						1
		FMBEDDED SYSTEM AND VEHICLE NETWORKING				
Intro		EMBEDDED SYSTEM AND VEHICLE NETWORKING	et A	rchi	tecture) (AR
		Embedded Systems -built in features for embedded Targ				
proce	essor) –	b Embedded Systems –built in features for embedded Targ selection of Embedded processor – DMA- memory devices –	Mem	nory	mana	igemei
proce meth	essor) – ods-merr	b Embedded Systems –built in features for embedded Targ selection of Embedded processor – DMA- memory devices – ory mapping, cache replacement policies- Timer and Countir	Merr ng de	nory evice	mana es, Wa	igemei atchdc
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DIRECTOR Centre for Academic Courses Anna University, Chennai-600 025

PRACTICALS

- 1. Study and testing of Lead acid battery used in vehicles
- 2. Study and testing of starting motor and alternator used in vehicles
- 3. Simulation and analysis of automotive Stator motor and Alternator using any e-CAD tools
- 4. Simulation of single-phase half and full wave-controlled converter fed RLE load using any e-CAD tools.
- 5. Simulation of three phase half and full controlled converter fed RL load using any e-CAD tools.
- 6. Computer based data acquisition for vibration measurement using Accelerometer in the Single-Phase Induction motor.
- 7. Computer based data acquisition for the Temperature measurement using thermocouple and LVDT
- 8. Computer based programming exercises / Experiments with Embedded Kit using Embedded 'C 'for
 - a) Interfacing of input devices (Switches and keypad)
 - b) Interfacing of output devices (Actuators and Display Devices)
- 9. Computer based programming exercises / Experiments with Embedded Kit using Embedded 'C' for
 - a) Timers / Counters
 - b) Interrupts
- 10. Using DSO to measure and analyze the following
 - a. Repetitive ringing, sine wave & sine with glitch signals
 - b. CAN bus & I2c protocol signals
 - c. Different waveforms using Functional generator

TOTAL : 90 PERIODS

COURSE OUTCOMES:C01Develop an understanding of the significance of electrical circuits, starter batteries, and the
starting and charging system within vehiclesC02Provide an illustrative explanation of the construction, principles, and speed control mechanisms
utilized in induction motorsC03Gain exposure to and understand the necessity of power electronics devices, controlled
rectifiers, AC voltage controllers, and choppers in automotive applicationsC04Categorize and elucidate the operational principles of various types of transducers and signal
conditioning employed in vehiclesC05Understand and differentiate the conventional and modern architecture networking in vehicles

TEXT BOOKS:

1. Bosch Automotive Electrics and Automotive Electronics Systems and Components, Networking and Hybrid Drive, 5th Edition, 2007, ISBN No: 978-3-658-01783-5

2. Ned Mohan, T.M.Undeland, W.P.Robbins, "Power Electronics: Converters, applications and design", John Wiley and Sons, 3rd Edition (reprint), 2009

REFERENCES:

- 1. Rashid, M.H., "Power Electronics Circuits, Devices and Applications", PHI, Fourth edition, 2014.
- 2. NPTEL Lecture Series on "Power Electronics" by Dr.B.G.Fernandes, IIT Bombay
- 3. Allan R. Hambley, "Electrical Engineering -Principles & Applications", 2019, 6th Edition, Pearson Education
- 4. V. D. Toro, Electrical Engineering Fundamentals, 2nd edition. PHI, 2014
- 5. R. L. Boylestad and L. Nashelsky, Electronic Devices and Circuit Theory, 11th edition. Pearson, 2012

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AVG	3	3	3	3	3	3	3	3	2



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AM32	205	VEHICLE MANAGEMENT SYSTEMS	Т	Ρ	С
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		ECTIVES:			
1.		rstand the basics of control system used in automobiles			
2.		nize the electronically controlled system used in driving mech			1
3.		rstand the working principle of driver modelling and power tra	in cont	roi sys	tems.
4. 5.		ify the control system used in hybrid and electrical vehicles. ate the need of automated transport systems			
5.	TO musu				
UNIT		INTRODUCTION			9
Comp	onents o	chassis management system - role of various sensors and	actuat	ors pe	rtainin
		em – construction – working principle of wheel speed sense			
		brake pressure, steering torque, fuel level, Engine and vehicle			
		DRIVELINE CONTROL SYSTEM			9
		- cylinder cut - off technology, Gear shifting control - Tracti			
		- Adaptive cruise control, throttle by wire. Steering - power	steerir	ng, col	lapsible
and ti		ering column – steer by wire.			
UNIT		SAFETY AND SECURITY SYSTEM			9
		belt tightening system, collision warning systems, child Loc	rk ant	i-lock	
		n enhancement, road recognition system, Anti-theft techn	•		
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sysier		r plata coding, control locking system			
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5. Bosch, "Automotive Handbook", 6th edition, SAE, 2004.

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AVG	3	3	3	3	3	3	3	3	2



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AM32	211	ENGINE /	AND VEH	ICLE TES	TING LAE	BORATOR	Y L	Т	Ρ	С		
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COU	RSE OBJE	CTIVES:										
1.	To impart	knowledg	je in auto	motive Er	nission m	leasureme	nt and m	ethods	s of t	esting		
	engines.											
2.			ferent mea	asuring tec	hniques c	of pollutants	s like UBH	IC, CO	, NO>	, CO		
	and smoke.											
3.						arameters	for differe	nt eng	ine m	odels		
4.	To learn re											
5.	To unders	tand the a	djustment	of play in	various a	utomobile (componer	nts.				
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2.						hrake leve	r and stee	rina w	heel			
2.		Adjustment of pedal play in clutch, brake, hand brake lever and steering wheel orientation.										
3.		lignment i	n four whe	elers.								
4.					uspensio	n systems.	1 miles					
5.		h body and			_		1.1					
			100	-	-		TOTAL	: 45	PER	IODS		
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CO2	Differentia				arameters	of Petrol e	ngines					
	Differentia	Differentiate the variation performance parameters of diesel engines										
CO3	Learn removal and fitting of automotive accessories											
						nobile com						
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AM3351 ELECTRIC AND HYBRID VEHICLES

L T P C 3 0 0 3

COURSE OBJECTIVES:

- 1. General aspects of Electric and Hybrid Vehicles (EHV), including architectures, modeling, sizing, sub-system design and hybrid vehicle control.
- 2. Understand about vehicle dynamics,
- 3. Design the required energy storage devices,
- 4. Select the suitable electric propulsion systems and
- 5. Understand of hybrid electric vehicles.

UNIT I NEED FOR ALTERNATIVE SYSTEM

Need for hybrid and electric vehicles – main components and working principles of a hybrid and electric vehicles, Different configurations of hybrid and electric vehicles. Comparative study of diesel, petrol, hybrid and electric Vehicles. Advantages and Limitations of hybrid and electric Vehicles. Case study on specification of electric and hybrid vehicles.

UNIT II DESIGN CONSIDERATIONS FOR ELECTRIC VEHICLES

Design requirement for electric vehicles- Range, maximum velocity, acceleration, power requirement, mass of the vehicle. Various Resistance- Transmission efficiency- Electric vehicle chassis and Body Design, Electric Vehicle Recharging and Refueling Systems

UNIT III ENERGY STORAGE DEVICES AND SOURCES

Battery Parameters- - Different types of batteries. Battery Chemistry, Battery Modelling, Battery Management System, Thermal Management system. Ultra-capacitors. Fuel Cell, Characteristics-Fuel cell types- Electrolytic reactions of fuel cell. Cell Chemistry.

UNIT IV MOTORS AND CONTROLLERS

Types of Motors, Characteristic of DC motors, AC single phase and 3-phase motor, PM motors, switched reluctance motors, Motor Drives and speed controllers, Torque Vectoring, Regenerative Braking. Rectifiers, Inverters, DC/DC converters.

UNIT V SUBSYTEMS OF HYBRID AND ELECTRIC VEHICLES

Power Split devices for Hybrid Vehicles - Operation modes - Control Strategies for Hybrid and Electric Vehicle- Economy of hybrid Vehicles.

COURSE OUTCOMES: PROGRESS THROUGH KNOWLEDGE

- CO1 Understand need and working of different configurations of hybrid and electric vehicles
- **CO2** Design and develop basic systems of electric vehicles and hybrid electric vehicles.
- **CO3** Choose proper energy storage systems for EV applications
- **CO4** Choose a suitable drive system for developing an electric and hybrid vehicle depending on resources
- **CO5** Understand basic operation of power-split device and control Strategies for hybrid and electric vehicle.

TEXTBOOKS:

- 1. James Larminie and John Lowry, "Electric Vehicle Technology Explained "John Wiley & Sons,2003
- 2. Iqbal Husain, "Electric and Hybrid Vehicles-Design Fundamentals", CRC Press, 2003
- 3. Mehrdad Ehsani, "Modern Electric, Hybrid Electric and Fuel Cell Vehicles", CRC Press,2005

Attested

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REFERENCES:

- 1. Ron Hodkinson, "Light Weight Electric/ Hybrid Vehicle Design", Butterworth Heinemann Publication, 2005
- 2. Lino Guzzella, "Vehicle Propulsion System" Springer Publications, 2005

COs			P	PSOs					
	1	2	3	4	5	6	1	2	3
1	3	3	3	3	3	3	3	3	2
2	3	3	3	3	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2



AM3001	ALTERNATIVE FUELS AND PROPULSION	L	Т	Ρ	С
	SYSTEMS			Atte	ted

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0011							
	RSE OBJECTIVES:						
1.	To acquire knowledge on availability of renewable fuels in the world and the technologies used for biofuel production						
2.	To understand the challenges and difficulties involved in using alternative fuels in interna combustion engines						
3.	To acquire complete knowledge on availability of possible alternate fuels and their properties to use as fuel in CI and SI engines						
4.	To explore the possible methods of using all the renewable fuels in SI and CI engines						
and analyze the engines behavior with different fuels and methods							
5.	To develop a complete understanding of changing the engine system, modifying the fuel for efficient use in engines						
UNIT							
Need	for alternative fuels. World and Indian energy scenario on alternative fuels. Production						
	ologies for biofuels for internal combustion engines- Pyrolysis, gasification, digestion.						
UNIT	II ALCOHOLS 9						
Alcoh	ols as fuels. Production methods of alcohols. Properties of alcohols as fuels. Methods						
of usi	ng alcohols in CI and SI engines. Blending, dual fuel operation, surface ignition and						
	enated additives. Performance, emission and combustion characteristics in CI and						
SI eng	gines. Calculation of Performance parameters. Recent Trends.						
UNIT	III VEGETABLE OILS 9						
	us vegetable oils and their important properties. Different methods of using vegetable oils						
	getable oils as fuel. Calculation of Performance parameters. Recent Trends.						
UNIT							
with engir	uction methods of hydrogen. Combustive properties of hydrogen. Problems associated hydrogen as fuel and solutions. Different methods of using hydrogen in SI and CI nes. Performance, emission and combustion analysis in engines. Hydrogen storage ety aspects of hydrogen. Recent Trends in Hydrogen research						
UNIT	V BIOGAS, LPG AND NATURAL GAS 9						
	luction methods of Biogas, Natural gas and LPG. Properties studies. CO2 and H2S						
scru and	bbing in Biogas., Modification required to use in SI and CI Engines- Performance emission characteristics of Biogas, NG and LPG in SI and CI engines. Recent Trends in						
engi	ne research. TOTAL: 45						
COUF	RSE OUTCOMES:						
CO1	To acquire knowledge on availability of renewable fuels in the world and the technologies used for biofuel production						
CO2	To understand the challenges and difficulties involved in using alternative fuels in interna						
CO3	combustion engines To acquire complete knowledge on availability of possible alternate fuels and their						
CO4	properties to use as fuel in CI and SI engines To explore the possible methods of using all the renewable fuels in SI and CI engines						
604	and analyze the engines behavior with different fuels and methods						
CO5	To develop a complete understanding of changing the engine system, modifying the fuel for efficient use in engines						
REFE	RENCES:						
1.	Richard L Bechtold P.E., Alternative Fuels Guide book, Society of Automotive						

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Engineers, 1997 ISBN 0-76-80-0052-1.

- 2. Donald Klass, Biomass for Renewable Energy, Fuels, and Chemicals, 1998, Academic Press, ISBN: 978-0-12-410950-6.
- 3. Ayhan Demirbas, 'Biodiesel A Realistic Fuel Alternative for Diesel Engines', Springer-Verlag London Limited 2008, ISBN-13: 9781846289941
- 4. Gerhard Knothe, Jon Van Gerpen, Jargon Krahl, The Biodiesel Handbook, AOCS Press Champaign, Illinois 2005.
- 5. Technical papers of SAE on Biofuels (Alcohols, vegetable oils, CNG, LPG, Hydrogen, Biogas etc.).
- 6. Science direct Journals (Biomass & Bio energy, Fuels, Energy, Energy conversion Management, Hydrogen Energy, etc.) on biofuels.

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	2	3	2	3	3	3	2
2	3	3	2	3	2	3	3	3	2
3	3	3	2	3	2	3	3	3	2
4	3	3	2	3	2	3	3	3	2
5	3	3	2	3	2	3	3	3	2
AVG	3	3	2	3	2	3	3	3	2



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AM300)2	AUTOMOTIVE AERODYNAMICS	L	Т	Ρ	С
			3	0	0	3
COUR	SE OBJ	ECTIVES:				
4		and the former Querements influencing dress				
		and the forces & moments influencing drag he techniques of detail and shape optimizations for cars, con	nmor	aialyr	biolo	c and
	motorcy		IIIIei		enicie	s anu
		to experimental testing and instrumentation				
0.						
UNIT I		SCOPE OF VEHICLE AERODYNAMICS				9
Scope	of vehic	le aerodynamics. Properties of incompressible fluids. Exter	rnal a	and in	terna	I flow
phenor	mena rel	ated to vehicles. Causes and effects of aerodynamic forces a	and r	nome	nts. Ir	npact
of road	d load o	n vehicle motion. Performance potential, Fuel Consumptio	n ar	d fue	l eco	nomy
calcula	tions. St	rategies for low fuel consumption.				-
UNIT I		AERODYNAMIC DRAG OF PASSENGER CARS				9
		g fractions and their local origins – forebody, windshield and				
		view and side panels, underbody, wheels and wheel housin				
		jies for aerodynamic development – Detail optimization,	Sha	pe op	otimiz	ation,
Facelli	t, Adapta	tion of add-on devices.				
		AERODYNAMIC DRAG OF COMMERCIAL VEHICLES				9
-		en tractive resistance, drag and fuel consumption. Aerodyna	amic	drag	neffi	-
		ehicles. Drag reduction on delivery vans, trucks, and buses				
		Vehicle soiling types, causes, effects and control measures			aono	00.00
UNIT I		MOTORCYCLE AERODYNAMICS				9
	-	of motorcycle aerodynamics. Riding dynamics and i			-	
aerody	mamics.	Methods of measurement in road tests. Rider influence	es -	rider	and	pillion
passer	nger. Clo	thing and helmets. Case studies on racing models.				
		EXPERIMENTAL TESTING AND INSTRUMENTATION				9
		ypes and Principle. Limitations with reduced scale models.				
		rs – Wind tunnel balance, hotwire anemometry, Pitot tube a				
		chniques – Smoke, wool tuft, Particle image velocim luid dynamics.	etry.	muro	aucia	
compu			-	то	TAL:	45
COUR	SE OUT	COMES:				
		nend the forces & moments influencing drag				
		the techniques of detail and shape optimizations for cars				
CO3	Interpret	the strategies of drag reduction in commercial vehicles				
		ate the factors influencing drag on motorcycles				
CO5	Expose	o experimental testing and instrumentation				
TC \/ T						
	BOOKS:			tina"	امم	
1.		pe, Jewel B. Barlow, William H. Rae "Low-speed wind tunne Third addition, 4000	ei les	ung ,	JOUN	vviiey
•		Third edition, 1999	4 - 1		1	- 1- 1 - 1
2.		W.H. – "Aerodynamic of Road Vehicles – From Fluid M			to V	enicle
	Engine	ering", Society of Automotive Engineers, U.S, Fourth edition,	, 199	8		
				(Here	to J
					mes	and and

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- 1. R.H. Barnard "Road vehicle aerodynamic design, An Introduction", Mechaero publications, Third edition, 2010
- 2. T. Yomi Obidi "Theory and Applications of Aerodynamics for Ground Vehicles", SAE International, 2014

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
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3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2



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AM30	003	AUTOMOTIVE FAULT DIAGNOSIS	L	Т	Р	С
			3	0	0	3
COU	RSE OBJ	ECTIVES:	-		-	
To im	port know	ledge on				
1.		ance procedure				
2.		and subsystem maintenance				
3.		ssion system maintenance				
4.		l system				
5.		itioning and body repair				
UNIT		MAINTENANCE, WORKSHOP PRACTICES, SAFET	Y AND	тоо	LS	9
Autor Perso tools	notive sei onnel, ma	enance – importance, classification of maintenance wo vice procedures – workshop – types - operations – w chines and equipment, vehicles, fire safety - First aid. E ing instruments –Scheduled maintenance services – s	rk-basi orksho Basic to	c prot p man ools –	olem di lual specia	Safety – I service
UNIT	11	ENGINE AND SUBSYSTEM MAINTENANCE				9
Engin under syste	ne service rside, fron m, Intake	 Dismantling of Engine components - Engine tunin t, top, ancillaries- Service of basic engine parts, cooling and Exhaust system, electrical system - Electronic ervice - fault diagnosis- servicing emission controls. 	and lu	oricati	ng syst	g on the tem, fuel
UNIT		TRANSMISSION AND DRIVELINE MAINTENANCE	/			9
servic	cing of un	ransmission, transaxle- road testing- Removing and versal joint and constant velocity joints- Rear axle sengs- servicing differential assemblies- fault diagnosis.	rvice p	oints-		
UNIT	IV	STEERING, BRAKE, SUSPENSION, WHEEL MAIN	FENAN	ICE		9
brake absor fitting steeri	es. Inspec bers. Dis of tires, t	ntenance and Service of Hydraulic brake, Drum braktion, Maintenance and Service of Mc person strut, co mantling and assembly procedures. Wheel alignment re wear and tire rotation. Inspection, Maintenance and h, steering gear box service- Rack and pinion, Recircula system.	il sprin and ba Servic	g, leat lance, e of st	f spring remov eering	g, shock ving and linkage,
UNIT	V	AUTO ELECTRICAL, AIR CONDITIOING AND VEH MAINTENANCE	ICLE E	ODY		9
Maint	enance o	batteries, starting system, charging system and body	/ electi	ical -	-ault d	iagnosis
using	Scan too	Is. Maintenance of air conditioning parts like compres	sor, co	onden	ser, ex	pansion
		or - Replacement of hoses- Leak detection- AC Chargi	ng- Fa	ult Dia	ignosis	; Vehicle
body	repair like	panel beating, tinkering, soldering, polishing, painting.				
			TO	TAL:	45 PI	ERIODS
	RSE OUT					
		letion of the course student can able to understand				
CO1		ortance of maintenance				
CO2		iems of engine				
CO3	Transmi					
CO4	Electric					
CO5	Body re	pair				
					Att	ested

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TEXT BOOKS:

- 1. Ed May, "Automotive Mechanics" Volume One, Mc Graw Hill Publications, 2006
- 2. Ed May, "Automotive Mechanics" Volume Two, Mc Graw Hill Publications, 2006

REFERENCES:

- 1. Bosch Automotive Handbook, Tenth Edition, 2018
- 2. Vehicle Service Manuals from different manufactures
- 3. William Crouse, Donald Anglin Automotive Mechanics
- 4. Denton, Advanced Automotive Fault Diagnosis Automotive Technology : Vehicle Maintenance and Repair, Routledge, 2012

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
2	3	2	2	2	2	2	3	3	2
3	3	2	2	2	2	2	3	3	2
4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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	AUTOMOTIVE INSTRUMENTATION AND TESTING	L	T	Ρ	C
		3	0	0	3
COURSE OF					
	vide theoretical and applicative knowledge in automobile to				
	ntify the various instruments for measuring force, torque, p	oressu	ire, te	mpera	ature,
	ow, velocity and rotational speed.				
3. To en	nance the knowledge of students regarding the experiment	al met	thods	follov	ved in
indust					
	niliarize the students on standard test codes.				
5. To im	part skills on the testing procedure followed for evaluating t	orake,	engin	e and	ł
UNIT I	MECHANICAL MEASUREMENT				9
Introduction t	o measurements – Construction, principle, working of Inst	rumen	ts for	meas	suring
force, torque	pressure, temperature, fluid flow, velocity, rotational speed	d.			-
UNIT II	VIBRATION AND BODY TEST				9
Vibration me	asurement instrument – accelerometer and signal condition	ning. D	ynam	nic	-
	ed testing, methodology, vehicle acceleration measuremen				tion.
	r test, dolly role over fixture, photographic / video coverage	. Vehi	cle ro	of stre	ength
test –. Door s	system crush test – wind tunnel tests.				-
UNIT III	CRASH AND BRAKE TEST				9
Crash tests -	standards - road hazard impact test for wheel and tyre as	sembli	ies, te	st	
	ailure and performance criteria. Bumpers - types of tests, p				ed
collision barr	er test, procedure, performance criteria. Air and hydraulic l	orake	test, a	air bra	ke
	es test, performance requirements.				
UNIT IV	ENGINE EXPERIMENTAL TECHNIQUES				9
I.S Code for	Engine testing – Instruments for performance testing of end	gine, li	nstrur	nenta	tion
	Engine testing – Instruments for performance testing of eng phoise, vibration in cylinder, different types of engine tests				
for measuring	Engine testing – Instruments for performance testing of eng g noise, vibration in cylinder, different types of engine tests				
for measuring the industry. UNIT V	y noise, vibration in cylinder, different types of engine tests	are p	erform	ned w	ithin
for measuring the industry. UNIT V Laboratory te	y noise, vibration in cylinder, different types of engine tests VEHICLE EXPERIMENTAL TECHNIQUES ests- test tracks - Endurance Tests - Dynamic cornering f	are po atigue	erform	ned w	ithin
for measuring the industry. UNIT V Laboratory te	y noise, vibration in cylinder, different types of engine tests VEHICLE EXPERIMENTAL TECHNIQUES ests- test tracks - Endurance Tests - Dynamic cornering f procedure, bending moment and radial load calculations.	are po atigue	erform , dyna	ned w amic	ithin 9
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1 DIRECTOR Centre for Academic Courses Anna University, Chennai-600 025

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3	3	3	3	3	2
2	3	3	3	3	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2



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AM3005	AUTOMOTIVE MATERIALS	L	Т	Ρ	С
		3	0	0	3
COURSE OBJ	ECTIVES:			•	
1. To know	ledge on properties of engineering materials				
2. To sele	t suitable materials for design				
3. To sele	t Materials for engine and transmission systems				
4. To sele	t materials used for automotive structures.				
5. To sele	t electronic materials for automotive applications				
	ENGINEERING MATERIALS AND THEIR PROPERTIE	S			9
properties, dis materials sele	ineering materials - the evolution of engineering material playing material properties using materials selection char ction and design, Materials and the environment-sel	ts, F	orces	for ch	ange ir
automotive, ae	rospace, marine and defense applications				
UNIT II	BASIS OF MATERIAL SELECTION				9
Manufacturing design, Proces cost, Energy co	s - types of design, design requirements, Function, Materi processes - Materials processing and design processes s attributes, Systematic process selection, Process selection onsumption for production, Material costs, Availability, Rec Computer aided selection. Case study	s and ction	d their diagra	influe ams, F	nce or Process
UNIT III	MATERIALS FOR ENGINES AND TRANSMISSION S	YST	EMS		9
	ction for IC engines: Piston, piston rings, cylinder, Engin				
	er Liners, Radiator fins, Connecting rod, Cam and Cam ox, Gears, Splines, Clutches, Turbo charger plates	Sha	aft, Cra	ank sh	aft, Fly
UNIT IV	MATERIALS FOR AUTOMOTIVE STRUCTURES				9
absorbers, Pre	ction for bearings, leaf springs, Coil spring, chassis & opeller shaft, axle shaft, wind screens, panels, brake imping and antifriction fluids, Tyres and tubes				
UNIT V	ELECTRONIC MATERIALS FOR AUTOMOTIVE APPI		TION	S	9
Materials for e	ectronic devices meant for engine control, ABS, Steering nti-fog, Head lamps, Air bag, Adaptive cruise control.				
	TOT	AL :		45 PE	RIODS
COURSE OUT	COMES:				
CO1 Summa	rize properties of engineering materials				
	suitable materials for design of automotive components				
CO3 Select N	laterials for IC engine and transmission systems				
CO4 Recomr	nend the materials used for automotive structures.				
CO5 Decide	suitable electronic materials for automotive electrical and e	lectro	onics a	pplica	tions
	: Elmarakbi," Advanced Composite Materials for Autor al Integrity and Crashworthiness", John Wiley & Sons Ltd			olicatio	ons - eight,

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- 2. Hiroshi Yamagata," The Science and Technology of Materials in Automotive Engines", Woodhead Publishing, 2005
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COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	2	2	2	2	2	2	3	3	2
2	3	3	3	3	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	2.8	2.8	2.8	2.8	2.8	2.8	3	3	2



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COURSE OBJECTIVES 1. To introduce the i 2. To understand the 3. To initiate the idea 4. To understand the 5. To design a product the idea UNIT I INTROD Need for developing product development product development product concurrent enging UNIT II CUSTO Identifying customer nerveds need gathering methods and the idea ign specification-case UNIT III CREAT Creative thinking method functional decomposition methods-TRIZ- axiomatt product design, design ign ign ign ign ign ign ign ign ign	mportance of product design e needs of a customer towards a produ- a of creativeness on product e decision-making concepts. Intervention based on cost frame and need of the JCTION Jucts – product policy of an organization –the design process – relevance of pro- standards- societal considerations cess – various phases of product developments- relevance of market re- neering- reverse engineering MER NEEDS eds –voice of customer –customer po- thods – affinity diagrams – needs impo- ve benchmarking- quality function deplo	De custon on -the im oduct life in engine elopment esearch- populatior ortance- e	portan cycle i eering -plann select	ss d ing	ues in esign g for p	design – –generic
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advantages, working pri Functional Analysis Syst UNIT IV DECISIO Decision making –decisio Pugh concept selection introduction to embodime	uidelines for metallic and non-metallic					
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	eeds of a customer towards a product creativeness on product ecision-making concepts.	customer				

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COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3	3	3	3	3	2
2	3	3	3	3	3	3	3	3	2
3	3	3	3	3	3	3	3	3	2
4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2



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AM30	07	AUTOMOTIVE SAFETY	L	Т	Ρ	С
			3	0	0	3
COUF	RSE OBJ	ECTIVES:				
1.	To intro	duce vehicle structural crashworthiness and crash testing				
2.		duce Occupant safety system				
3.	To get t	ne knowledge in Active Safety in the vehicle and function	of AD	AS.		
4.		erstand the fundamentals of sensor and to detect the			round	I the
	vehicle a	and the concept of the connected vehicle.				
5.	To Unde	erstand SAE Levels of Driving Automation.				
UNIT		CONCEPTS OF AUTOMOTIVE SAFETY				9
		ety: Introduction and Types. Active safety: driving safe				
		afety, operating safety. Passive safety: Design of body f				
		Safety Cage. Optimum crash pulse, deceleration on impa	ict wit	h stat	ionary	and
		cles. Design for Crashworthiness. NCAP. ISO26262		-		
UNIT		PASSIVE SAFETY EQUIPMENTS AND CONVENIENC				9
		belt tightener system and importance, collapsible steering Designing aspects of automotive bumpers and materials t			•	
		ustment, central locking system, Tire pressure Monitoring				
	•	ated wiper system.	J 3931	, 10		11301
UNIT						9
		g system, Stability Control. Adaptive cruise control, Lane	Keer	Assi	st Svs	-
		ng, avoidance system, Blind Spot Detection system, Driv				
	m. ADAS					
UNIT		VEHICLE INTEGRATION AND CONNECTED VEHICLE	Ē			9
Looki	ng out se	ensors and Looking in sensors, Intelligent vision systen	n, Ve	hicle	Integr	ation
syster	m. Global	Positioning System. Vehicle Navigation System. Road Network	etwor	k, V2∖	/.	
UNIT		AUTONOMOUS VEHICLE				9
		f Driving Automation, Level 0 - No Driving Automatic				
		vel 2 – Partial Driving Automation, Level 3 – Conditiona	il Driv	ving A	utoma	ition,
Level	4 – High	Driving Automation, Level 5 – Full Driving Automation.		45.5		
0		COMES:	TAL:	43 F	PERIO	D2
COOP	3E 001	COMES:				
CO1	Know a	pout the concept of crumble zone and vehicle structural	crack	worth	inocc	and
001	crash te		Clasi	woru	111033	anu
CO2		e various types of Occupant safety system				
CO3		bout Active Safety in the vehicle and avoid crash and func	tion c	of ADA	S.	
CO4		and the fundamentals of sensor and to detect the obstacl				hicle
		concept of the connected vehicle.				
CO5		and SAE Levels of Driving Automation.				
	BOOKS:					
1.		lacic, Michel Parent, Fumio Harashima – "Intelligent Vehi	cle Te	echnol	ogies	
~		and Applications" -Butterworth-Heinemann, 2001		۰. ۱۰		. "
2.		k, HP. Trah, Y. Suzuki, I. Yokomori - "Sensors for Autom	otive	Appli	cation	s"-
0		VCH Verlag GmbH & Co. 2003	۳ <u>۰</u> ″۱۸	Vilor	Ord a-	lition
3.	Robert 2007	Bosch GmbH - "Safety, Comfort and Convenience System	п s - V	viiey;	sia ec	nnon
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COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	3	3	3	3	3	2
2	3	2	2	3	3	3	3	3	2
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5	3	2	2	3	3	3	3	3	2
AVG	3	2	2	3	3	3	3	3	2



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UNIT IV Current and modern vali techniques. dependency validation of Applications UNIT V Introduction and Error-Hu in Autonomo and Ethical E in Autonomo operation COURSE OI CO1 Demo its cla	and multiple sensor fusion-AI algorithms for sensing and ima				
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modern vali techniques. dependency validation of Applications UNIT V Introduction and Error-Hu in Autonomo and Ethical E in Autonomo operation COURSE OI CO1 Demo its cla	NETWORKING AND CONNECTED VEHICLES				9
techniques. dependency validation of Applications UNIT V Introduction and Error-Hu in Autonomo and Ethical E in Autonomo operation COURSE OI CO1 Demo its cla	future vehicle networking technologies- CAN, LIN, MOST				
dependency validation of Applications UNIT V Introduction and Error-Hu in Autonomo and Ethical D in Autonomo operation COURSE OI CO1 Demo its cla	dation and verification methods- software-in-the-loop, a				
Validation of Applications UNIT V Introduction and Error-Hu in Autonomo operation COURSE OU CO1 Demo its cla	he role of Functional Safety and ISO26262 within the ove				
Applications UNIT V Introduction and Error-Hu in Autonomo and Ethical E in Autonomo operation COURSE OU CO1 Demo its cla	between software engineering and control system-advance				
UNIT V Introduction and Error-Hu in Autonomo and Ethical D in Autonomo operation COURSE OI CO1 Demo its cla	afety-critical systems. connected vehicle control (CACC). Ve				
Introduction and Error-Hu in Autonomo operation COURSE OU CO1 Demo its cla	such as intelligent traffic signals, collaborative adaptive cruis	e and	veni	cie piai	ooning.
Introduction and Error-Hu in Autonomo and Ethical D in Autonomo operation COURSE OU CO1 Demo its cla	HUMAN FACTORS AND ETHICAL DECISION MAKING				9
and Error-Hu in Autonomo and Ethical E in Autonomo operation COURSE OU CO1 Demo its cla	o Human Factors-Human Performance: Perception and Atter		Situa	tion Aw	-
in Autonomo and Ethical E in Autonomo operation COURSE OF CO1 Demo its cla	man Reliability: Driver Workload and Fatigue-Emotion and Atten				
and Ethical E in Autonomo operation COURSE OI CO1 Demo its cla	us Vehicles and Assistive Technology-Designing ADAS Sys				
in Autonomo operation COURSE OU CO1 Demo its cla	ilemmas: Human Factors and Decision-Making Software-App				
operationCOURSE OFCO1Demoits cla	us Vehicles. International and national regulatory framework				
CO1 Demo its cla	5 ,				
CO1 Demo its cla		ΤΟΤΑ	L:	45 P	ERIODS
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	ITCOMES:	nicle te		0.	ncluding
	TCOMES: Instrate a comprehensive understanding of autonomous veh				
	TCOMES: Instrate a comprehensive understanding of autonomous veh ssifications, applications, and associated advantages and dis	sadva	sign		•
	TCOMES: Instrate a comprehensive understanding of autonomous veh ssifications, applications, and associated advantages and dis decision-making principles and path planning techniques	sadva to de		on met	
	TCOMES: Instrate a comprehensive understanding of autonomous veh ssifications, applications, and associated advantages and dis decision-making principles and path planning techniques hms for autonomous vehicles, utilizing various approaches a	sadva to de and va			id neural
	ITCOMES: Instrate a comprehensive understanding of autonomous veh asifications, applications, and associated advantages and dis decision-making principles and path planning techniques hms for autonomous vehicles, utilizing various approaches a ce and integrate sensor data using appropriate architectures,	sadva to de and va		ims, an	
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	TCOMES: Instrate a comprehensive understanding of autonomous veh ssifications, applications, and associated advantages and dis decision-making principles and path planning techniques hms for autonomous vehicles, utilizing various approaches a e and integrate sensor data using appropriate architectures, rks for perception and visualization in autonomous vehicles. networking technologies and communication protocols t	sadvai to des and va , AI ale to ena	gorith able	conne	ctivity in
Interd	ITCOMES: Instrate a comprehensive understanding of autonomous veh asifications, applications, and associated advantages and dis decision-making principles and path planning techniques hms for autonomous vehicles, utilizing various approaches a se and integrate sensor data using appropriate architectures, rks for perception and visualization in autonomous vehicles.	sadvai to de: and va , AI alg to ena unctior	gorith able	conne	ctivity in

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CO5 Evaluate and address human factors considerations, such as human performance, workload, and ethical decision-making, within the design and operation of autonomous vehicles, while understanding the regulatory frameworks governing their safe deployment.

TEXT BOOKS:

- 1. Nicu Bizon, Lucian Dascalescu, Naser Mahdavi Tabatabaei, "Autonomous Vehicles: Intelligent Transport Systems and Smart Technologies,". Nova Science Publishers, 2014.
- 2. Andreas Herrmann, Walter Brenner, Rupert Stadler, "Autonomous Driving: How the Driverless Revolution will Change the World", Emerald Publishing Limited ,2018.
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- 1. Nikolaus Correll, Bradley Hayes, et al., "Introduction to Autonomous Robots: From Kinematics to Path Planning,", The MIT Press, 2022.
- 2. George Dimitrakopoulos, AggelosTsakanikas, Elias Panagiotopoulos," Autonomous Vehicles: Technologies, Regulations, and Societal Impacts", Elsevier, 2021.
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COs			P	Ds				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	3	3	3	3	3	3	3	2
2	3	3	3	3	3	3	3	3	2
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5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2

PROGRESS THROUGH KNOWLEDGE

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AM30)09	DESIGN AND ANALYSIS OF EXPERIMENTS	L	Т	Ρ	С
			3	0	0	3
COUF	RSE OBJ	ECTIVES:				
1.		ify the key factors in designing experiments				
2.	To deve	lop appropriate experimental design				
3.	To analy	ze the data to derive valid conclusions.				
4.	To optin	nize process conditions by developing empirical models.				
5.	To Desi	gn robust products and processes using parameter desig	n app	broach		
UNIT		FUNDAMENTALS OF EXPERIMENTATION				9
Role	of experi	mentation in rapid scientific progress, Historical persp	ectiv	e of e	experir	nental
	aches, St iques.	eps in experimentation, Principles of experimentation. Intr	oduc	tion to	optimi	zation
UNIT		SIMPLE COMPARATIVE EXPERIMENTS				9
		of probability and statistics, Comparison of two mea multiple (more than two) means & ANOVA.	ns a	nd two	o varia	ances,
UNIT	111	EXPERIMENTAL DESIGNS				9
	n, analysi	ables, modifying the orthogonal arrays, selection of s s of experimental data. RESPONSE SURFACE METHODOLOGY			logona	
-		model, steepest ascent, second order model, regression	١			
UNIT	V	TAGUCHI'S PARAMETER DESIGN				9
Conce		ustness, noise factors, objective function & S/N ratios, inr	er-ai	ray ar	nd oute	-
	RSE OUT		ΓΟΤΑ	L:	45 PE	RIODS
CO1	Formula problem	te objective(s) and identify key factors in designing o	<u>.</u>			•
		appropriate experimental design to conduct experiments		a givei	n probl	em.
CO3		experimental data to derive valid conclusions.	-			
CO4		e process conditions by developing empirical models usir			ental d	ata.
CO5	Design	obust products and processes using parameter design a	ppro	ach.		
1.	NY, 200	mery DC, Design and Analysis of Experiments, 7th Editic			•	
	NY, 200		_	-	1	<i>.</i>

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COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
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4	3	3	3	3	3	3	3	3	2
5	3	3	3	3	3	3	3	3	2
AVG	3	3	3	3	3	3	3	3	2



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AM30	010	ENGINE COMBUSTION THERMODYNAMICS AND ENGINE HEAT TRANSFER	L	Т	Ρ	С
			3	0	0	3
COU		ECTIVES:				
1.	To rem	ember and understand the thermodynamic principles tion.	of ge	eneral	and	engine
2.		the knowledge in chemical kinetics involved in general a	and er	naine c	ombu	stion
3.		rstand different types of flames, their structures and ana				
	the flam		. <u>,</u>			
4.	To evalu analysis	ate the engine heat release rate and heat transfer mode	ls for	engine	e comb	oustion
5.		Jate the experimental methods on combustion and heat	trans	for ca	culatio	one for
J.		analysis.	tians		culatio	113 101
UNIT		INTRODUCTION TO COMBUSTION PROCESSES				9
		uel and Oxidizer – types – Various combustion modes-	Comh	ustion	in pre	-
		remixed turbulent combustion - Flame Speed – Burr				
		ustion process in IC engines.	g	. 010010	<i>y</i>	
UNIT		THERMODYNAMICS OF COMBUSTION				9
Thern	nodynami	cs of combustion - Thermodynamic Properties - Ideal	gas	law –	Gas r	nixture
		Stoichiometric combustion - Thermochemistry - Hess				
		Physics of combustion – Fick's law of species diffusion – C				
	dary layei		ü.,		•	
UNIT	111	NORMAL, ABNORMAL COMBUSTION IN SI ENGINES	3			9
Stage	es of comb	oustion – Flame propagation — Flame Limits – Flame Exti	nctior	n - Rate	e of pr	essure
rise -	Cycle to	cycle variation – Abnormal combustion – Theories of deto	natio	n – Eff	ect of	engine
opera	ating varia	bles on combustion –Example problems.				
UNIT		COMBUSTION AND HEAT TRANSFER IN IC ENGINES				9
		ay combustion theory – delay period – Peak pressure – Ca				
		perature calculations – Diesel knock. Basic definitions –				
		at transfer – Heat transfer, temperature distribution and the	nerma	l stres	ses in	piston
		 Cylinder head – fins and valves. 			··	
UNIT	V	EXPERIMENTAL INVESTIGATION OF COMBUST TRANSFER IN IC ENGINES	ION	AND	HEAT	Г 9
		tudies of combustion processes – Endoscopy Technique				
		st Processing for combustion parameters. Assembly – Te der liner – Cylinder head and engine valves.	mpera	ature n	neasur	ement
			TAL:	4	15 PEF	RIODS
COU	RSE OUT	COMES:				
CO1		mpletion the students summarize the thermodynamic p	orincip	les of	gener	al and
	<u> </u>	combustion.				
CO2		derstand the principle of engine combustion and the varion as the varion of engine heat transfer in detail	ous he	eat tra	nsfer r	nodels
CO3		Il have comment over on different flames and their im	porta	nce in	comb	oustion
	applicat	ons	•			
CO4		II understand thermodynamics of combustion, grasp th al combustion and heat transfer in engines	e kno	wledg	e of n	ormal,
CO5		so understand and apply the experimental techniqu tion and heat transfer processes in IC engines	es in	inve	stigatir	ng the
					Atte	sted

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- 2. Spalding.D.B., "Some fundamental of Combustion", Butterworth Science Publications, London, 1985.
- 3. Taylor. E.F. "The Internal Combustion Engines", International Text Book Co., Pennsylvania, 1982.
- 4. V.Ganesan, 'Internal combustion Engines', Tata McGraw Hill Book Co, Eighth Reprint, 2012.
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COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
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3	3	3	2	3	2	3	3	3	2
4	3	3	2	3	2	3	3	3	2
5	3	3	2	3	2	3	3	3	2
AVG	3	3	2	3	2	3	3	3	2



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AM30)11	FINITE ELEMENT METHODS IN AUTOMOBILE ENGINEERING	L	т	Р	С
			3	0	0	3
COUR	RSE OBJ	ECTIVES:				
1.		o the students with the Finite Element Analysis fundament				
2.		e the students to formulate the design problems into FEA				
3.		duce basic aspects of finite element technology, including	ng da	omain	discre	tization
J.		nial interpolation, application of boundary conditions				
4.		erstand the assembly of global arrays, and solution o	of the	resu	lting a	Igebraic
	systems					
5.		and how to use finite element analysis in engineering p	proble	ems a	nd ap	plication
		cluding stress, heat transfer, and vibration analysis				
		INTRODUCTION esign analysis-meaning and purpose, steady state, pro-			<u> </u>	9
struct Test f value	tural anal for conver problem	ncepts of FDM, FEM, FVM. Steps involved in FEM. ysis, heat transfer and fluid flow problems. Advantages gence. Element choice. Commercial finite element packag - Integral formulation for numerical solution - Variational in y formulation.	and ges. S	limitat olutio	ions o n of Bo	of FEM. oundary
UNIT	U	1D ELEMENTS				9
		beam elements in structural analysis. Bar Element – Stiffn	ass m	atrix I	Formul	-
		nomial methods. Boundary condition and assemblage				
		matrix. Global, local, natural coordinates.	Jonioe	p.o	Joann	olomon
UNIT		2D ELEMENTS	-			9
-		lements - Quadratic quadrilateral elements - Linear T	rianau	ular e	lemen	
bound eleme	dary cond ents. Intro	cations for plane stress, plane strain and axi-symmetric ition. Mesh generation techniques. Numerical integration duction to 3D Elements.				rametric
UNIT		STRUCTURAL AND DYNAMIC ANALYSIS				9
		ems in Solid mechanics. Dynamics problems representa				
		lation. Torsion of non-circular shaft - axisymmetric pro ysis of Chassis Frame, Whirling speed of propeller shaft, (
		of suspension system, impact, crash worthiness etc.	Juna	u and	119515 0	i gears,
		HEAT TRANSFER ANALYSIS AND FLOW ANALYSIS				9
		ems in fluid mechanics and heat transfer by conduction a		nvec	tion T	
		is. Case Studies like Heat transfer analysis of piston, fins.				ansiem
uieiiii	iai anaiyo		TAL:		45 PF	ERIODS
COU	RSE OUT					
CO1		mathematical model for solution of common engineering p	oroble	ms.		
CO2		ite simple problems into finite elements.	10010			
CO3		ructural, thermal, fluid flow problems.				
		ofessional-level finite element software to solve engine	erina	prob	lems	in Solic
CO4		ics, fluid mechanics and heat transfer.		1.00		
CO5	Derive e	element matrix equation by different methods by applying gration by parts	basio	c laws	in me	chanics
					. ~	
_	Inc.,Ne	nd,L.J., Applied Finite Element Analysis, Second Edition, w York, 1984		•		
2.		D. Cook, David S. Malkus, Michael E. Plesha, Robert J. V tions of finite element analysis", 4th edition, John Wiley &			•	a

applications of finite element analysis", 4th edition, John Wiley & Sons, 2007.Krishnamurthy,C.S., Finite Element Analysis, Tata McGraw Hill, 1987.

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- 7. Singiresu S. Rao, "The Finite Elements Methods in Engineering", 4th Edition, USA, 2005.

COs			P	Os				PSOs	
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3	3	3	2	3	2	3	3	3	2
4	3	3	2	3	2	3	3	3	2
5	3	3	2	3	2	3	3	3	2
AVG	3	3	2	3	2	3	3	3	2



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AM30)12	HYDRAULIC AND PNEUMATIC SYSTEMS	L	Τ	Ρ	С
			3	0	0	3
COUI	RSE OBJ	ECTIVES:				
1.	Tounda	erstand the basics of hydraulic and pneumatic systems				
<u>1.</u> 2.		nine the working of hydraulic power drives				
<u>2.</u> 3.		/ knowledge on fluid power elements				
4.		gn hydraulic and pneumatic systems				
5.		/ the concepts of programming in PLC circuits.				
UNIT		INTRODUCTION				9
		Iraulic fluids and air. Hydraulic fluids, types, factors affecting				
		laws- distribution of fluid power- selection, power unit.				
		king and seals, packing standards. Comparison between				
syster	m. energy	losses in hydraulic systems- Symbols of pneumatic and hy	/draul	ic ele	ments.	
		PNEUMATIC SYSTEMS nent. Elements of pneumatics, preparation of compressed	oir	nolin	a 004	9
		r. conditioning and distribution of compressed air. pneumati				
		mpressors, types, Air motors, control valves, actuators and i				
		eral approach of system design, travel step diagram. Types s ethod. K.V.Mapping for minimization of logic equation. Simple				Lascaue
step (counterm	ethod. K.V.Mapping for minimization of logic equation. Simp	pie ci	cuits.		
JNIT		HYDRAULIC SYSTEMS	-			9
		ps and motors - types, characteristics., construction det	ails	Valve	s for a	
		and pressure types and construction details. Power pack ele				
		ittings. seals and packing. accessories used in fluid power				
		ms. Selection criteria for cylinders, valves, pipes.	Syste	////5	manne	
iyura	une syste	nis. Selection chiena for cynnders, valves, pipes.				
UNIT	IV	SERVO AND PLC SYSTEMS				9
Electr	o pneum	atics, ladder diagram. Servo and Proportional valves - typ	bes, c	perat	ion, ap	plication
		ical servo systems. PLC-construction, types, operation, r				
circuit	ts		Ū		0	
UNIT	V	AUTOMOTIVE APPLICATIONS				
			ppol	motic		9
		g mechanism, power steering, fork lift hydraulic gear, hydro				
		ance and trouble shooting. Design and analysis of a hydrauli	ic/Pn	euma	tic syst	iem-Cas
Study						
			TO	TAL:	45 F	PERIOD
cou	RSE OUT	COMES			401	LINIOD
0001						
CO1	Remem	ber the importance of Fluid power				
CO2		e the use of various fluid power elements				
CO3		and the concepts of various fluid power elements				
CO4		e knowledge on PLC and electro pneumatics				
CO5		stand the various hydraulic circuits used in automobiles				
		,				
ТЕХТ	BOOKS					
		Esposito, "Fluid power with applications" , 5th Edition, Pears	son E	ducat	ion 20	03.
		r, "Oil Hydraulics: Principles and Maintenance", Tata McGra				
- 2.	iviajumua			n, 200	/4	

3. Majumdar, "Pneumatic system: Principles and maintenance", Tata McGraw Hill,2004

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- 1. Anthony Espisito, "Fluid Power with Application", Pearson Education (Singapore) Pte.Ltd, Delhi, India, Fifth Edition, First Indian Reprint, 2003
- 2. Werner Deppert and Kurt Stoll, "Pneumatic Controls: An introduction to principles ", Vogel-Druck Wurzburg, Germany, 1975
- 3. Pippenger, J.J, "Industrial Hydraulic & Pneumatics", McGraw Hill, 2002

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
2	3	2	2	2	2	2	3	3	2
3	3	2	2	2	2	2	3	3	2
4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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AM30	013	IC ENGINE PROCESS MODELLING	L	Т	Ρ	С
			3	0	0	3
COUF	RSE OBJ	ECTIVES:				
1.	To impa	rt knowledge in modeling the Internal combustion engine p	roces	ses a	nd ac	quire
		ge in different types of engine models and their importance				•
2.		rstand the calculation of heat of reaction, air fuel ratio and		temp	eratu	re for
		ng a thermodynamic engine model.				
3.		re knowledge on the detailed concept of air standard, fuel	air cv	cle p	roare	ssive
•		al cycle simulation of SI engine.	un ey	0.0, p	regre	00110
4.		rstand the gas exchange process and develop models for the	he int	ake ai	nd ext	naust
••	process					
5.		lop a complete theoretical engine model for the SI engine	and	differ	entiat	e the
0.		om CI engine model.		unor	onnat	
UNIT		INTRODUCTION TO SIMULATION				9
		Simulation, Advantages of computer simulation, Classification	on of	ongin	- moo	
		ust flow models – Quasi steady flow -Filling and emptying -C				
		based in cylinder models. Step by step approach in S				
	•	delling softwares.	eng	ine s	mula	.1011.
UNIT			TUD	-		9
						-
		sses, Heat of reaction, measurement of URP, measuremen				
		equation for hydrocarbon fuels. Calculation of minimum				
		air required for combustion. Introduction, complete com				
		ant volume adiabatic combustion, constant pressure a	idiaba	ITIC CO	suamo	stion,
		diabatic flame temperature, isentropic changes of state.				
		SI ENGINE SIMULATION	<u> </u>			9
		ation with air as working medium, deviation between actua				
		is - Temperature drop due to fuel vaporization, full throttle of				
		calculation, part-throttle operation, engine performance a				
		ion. SI Engines simulation with progressive combustion. M	lodels	s for r	nass	burnt
fractio			0-00			
UNIT		SI ENGINE SIMULATION WITH GAS EXCHANGE PRO			<u> </u>	9
		s exchange process, Heat transfer process, friction calcul		•		
		s, validation of the computer code, engine performance simu				
		brake power, brake thermal efficiency, effect of speed				
		data. Case study using engine simulation Software. Overvie	ew of	CFD r	nodel	
UNIT		ENGINE SIMULATION FOR CI AND ADVANCED ENGI				9
		nultizone models for diesel engine combustion. Wiebe's Mod				
		del for diesel combustion. Heat release rate and heat transfe				
		ngine modeling for dual fuel engine- Multifuel engines.				
	• •	ess and validation of the models. Parametric studies	on si	mulat	ed er	ngine
perfor	rmance.					
				ΤΟΤΑ	L:	45
	RSE OUT					
CO1		nd the classifications and applications of engine cycle				
	• .	e major modeling and simulation methods and the influence	e of m	odel p	aram	eters
		e performance.				
CO2		the heat of reaction, fuel air ratio and flame temperat	ure f	or de	velopi	ng a
					•	-
- ··		ynamic engine model				
CO3			cycle	simu	ation	of SI
CO3		the air standard, fuel air cycle, progressive and actual	cycle	simu	ation	of SI
	engine.	the air standard, fuel air cycle, progressive and actual	-			
CO3 CO4	engine. Evaluate		-			

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	Create engine models for SI and CI engines and also can create models for advanced engine concepts
REFER	ENCES:
1.	Ashley Campbel, "Thermodynamic analysis of combustion engines", John Wiley & Sons, New York, 1986.
2.	Benson.R.S., Whitehouse.N.D., "Internal Combustion Engines", Pergamon Press, oxford, 1979
3.	Ganesan.V. "Computer Simulation of spark ignition engine process", Universities Press (I) Ltd, Hyderbad, 1996.
4.	John. B. Heywood, 'Internal Combustion Engines'", Tata McGraw Hill Co., Newyork, 2017.
5.	Ramoss.A.L., "Modelling of Internal Combustion Engines Processes", McGraw Hill Publishing Co., 1992.

COs			PSOs						
COS	1	2	3	4	5	6	1	2	3
1	3	3	2	3	2	2	3	3	2
2	3	3	2	3	2	2	3	3	2
3	3	3	2	3	2	2	3	3	2
4	3	3	2	3	2	2	3	3	2
5	3	3	2	3	2	2	3	3	2
AVG	3	3	2	3	2	2	3	3	2



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	014	INSTRUMENTATION AND EXPERIMENTAL L TECHNIQUES	Т	Ρ	С
		3	0	0	3
COU	RSE OBJ	ECTIVES:			
1.	To Stud	y the theory, construction and operation of different measureme	ent tec	hnolc	gy for
	automo	piles			
2.	To unde	erstand working principle of various instruments, transducers and	d their	appli	cation
		notive industry.			
3.		ire knowledge on various mechanical measurement instruments			
4.		y different types of instruments used for engine testing and its wo			
5.		uire knowledge in experimental methods for testing the vehi	cle w	th dif	feren
<u> </u>	instrum				
UNIT		MEASUREMENT SYSTEMS			9
		namic Measurement systems-importance of measurement systemeters			
		-applications - characteristics of measuring system-stati			
		of measuring system - Analysis of experimental detail, Error	analy	sis-typ	pes of
	s-limiting e		<u> </u>		
UNIT	11	TRANSDUCERS, MODIFIERS AND TERMINATING DEVICE	3		9
Trans	ducers fo	r Automotive Applications – Amplifiers-Classifications and applica	tion in	autor	nobile
		– Data Acquisition system - Analog and digital type DAS- Indica			
		-Signal Analysing with example of automobile applications.	,		
UNIT	ÍII	MECHANICAL MEASUREMENT			9
Instru	Imentatio	n for Measuring Weight, Force, torque, pressure, power, tempe	erature	e, flui	d flow
		nethods, vibration piezo electric effect, rotational speed. Me			
-				-	-
accel	eration ar	nd angular motion with respect to automobile applications			
UNIT	IV	ENGINE EXPERIMENTAL TECHNIQUES	Inct	umor	
UNIT I.S Co for Re tempe	IV ode for El esearch a erature Dy	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinder namic Cylinder pressure measurements.			flame
UNIT I.S Co for Ro tempo UNIT	IV ode for El esearch a erature Dy V	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinder /namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES	r gas	flow,	ntation flame 9
UNIT I.S Co for Ro tempo UNIT Labor	IV ode for El esearch a erature Dy V ratory test	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde (namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering	r gas	flow, ie, dy	flame flame 9 namic
UNIT I.S Co for Re tempe UNIT Labor radial	IV ode for El esearch a erature Dy V ratory test fatigue f	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation	r gas fatiguns. Im	flow, ie, dy pact	ntation flame 9 namic test -
UNIT I.S Co for Ro tempo UNIT Labor radial Bump	IV ode for El esearch a erature Dy V ratory test fatigue to pers - typ	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure	r gas fatigu ns. Im ure, p	flow, ie, dy pact erforr	ntation flame 9 namic test - nance
UNIT I.S Co for Ro tempo UNIT Labor radial Bump	IV ode for El esearch a erature Dy V ratory test fatigue to pers - typ	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance	r gas fatigu ns. Im ure, p e requi	flow, ie, dy pact erforr reme	ntation flame 9 namic test - nance nts.
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri	IV ode for El esearch a erature Dy V ratory test fatigue to bers - typ a. Air and	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde /namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance	r gas fatigu ns. Im ure, p	flow, ie, dy pact erforr reme	ntation flame 9 namic test - nance
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI	IV ode for El esearch a erature Dy V ratory test fatigue f bers - typ a. Air and	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance TC COMES:	r gas fatigu ns. Im ure, p e requi	flow, ie, dy pact erforr reme	ntation flame 9 namic test - nance nts.
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s	IV ode for El esearch a erature Dy V ratory test fatigue 1 bers - typ a. Air and RSE OUT	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance TC COMES: vill be able to	r gas fatigu ns. Im ure, p requi DTAL:	flow, ie, dy pact erforr reme	ntatior flame 9 namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s	IV ode for Elesearch a erature Dy V ratory test fatigue f bers - typ a. Air and RSE OUT students v	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance TC COMES:	r gas fatigu ns. Im ure, p requi DTAL:	flow, ie, dy pact erforr reme	ntatior flame 9 namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s CO1	IV ode for Elesearch a erature Dy V ratory test fatigue f bers - typ a. Air and RSE OUT students v Interpre develop	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedur hydraulic brake test, air brake actuator, valves test, performance TC COMES: vill be able to t the components of the automotive instruments and their function ments in this field.	r gas fatigu ns. Im ure, p requi DTAL:	flow, ie, dy pact erforr reme d the	ntatior flame namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI	IV ode for Elesearch a erature Dy V ratory test fatigue f bers - typ a. Air and RSE OUT students v Interpre develop Demons	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance TC TCOMES: vill be able to t the components of the automotive instruments and their function	r gas fatigu ns. Im ure, p requi DTAL:	flow, ie, dy pact erforr reme d the	ntatior flame namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s CO1 CO2 CO2 CO3	IV ode for El esearch a erature Dy V ratory test fatigue 1 bers - typ a. Air and RSE OUT students v Interpre develop Demons Underst	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde (namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedu hydraulic brake test, air brake actuator, valves test, performance TC COMES: vill be able to t the components of the automotive instruments and their function ments in this field. tartate their knowledge on transducers, modifiers and terminating of and mechanical measurement	r gas fatiguns. Im ure, p requi DTAL:	flow, le, dy pact erforr reme d the s	ntatior flame namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s COUI The s CO1 CO2 CO3 CO4	IV ode for Elesearch a erature Dy V ratory test fatigue for bers - typ a. Air and RSE OUT students v Interpre develop Demons Underst Experim	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde (namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedu hydraulic brake test, air brake actuator, valves test, performance TC COMES: //II be able to t the components of the automotive instruments and their function ments in this field. strate their knowledge on transducers, modifiers and terminating of and mechanical measurement ent the various procedure followed in the engine experimental term	r gas fatiguns. Im requi DTAL: ons an device	flow, le, dy pact erforr reme d the s	ntatior flame namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s COUI The s CO1 CO2 CO3 CO4 CO5	IV ode for Elesearch a erature Dy V ratory test fatigue for bers - typ a. Air and RSE OUT students v Interpre develop Demons Underst Experim	ENGINE EXPERIMENTAL TECHNIQUES ngine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedure hydraulic brake test, air brake actuator, valves test, performance TC COMES: vill be able to t the components of the automotive instruments and their function ments in this field. trate their knowledge on transducers, modifiers and terminating of and mechanical measurement ent the various procedure followed in the engine experimental techniques	r gas fatiguns. Im requi DTAL: ons an device	flow, le, dy pact erforr reme d the s	ntatior flame namic test - nance nts. 45
UNIT I.S Co for Ro tempo UNIT Labor radial Bump criteri COUI The s COUI The s CO1 CO2 CO3 CO4 CO5 TEXT	IV ode for Elesearch a erature Dy V ratory test fatigue for oers - typ a. Air and RSE OUT students v Interpre develop Demons Underst Experim Demons BOOKS: . Crouse Compa	ENGINE EXPERIMENTAL TECHNIQUES Ingine testing – Instrumentation for performance testing of engine and development, Instrumentation for noise, vibration, in cylinde (namic Cylinder pressure measurements. VEHICLE EXPERIMENTAL TECHNIQUES s- test tracks - Endurance Tests- crash tests- Dynamic cornering ests – procedure, bending moment and radial load calculation es of tests, pendulum test, fixed collision barrier test, procedu hydraulic brake test, air brake actuator, valves test, performance TC COMES: vill be able to t the components of the automotive instruments and their function ments in this field. t the ir knowledge on transducers, modifiers and terminating of and mechanical measurement tent the various procedure followed in the engine experimental techniques e W H and Anglin D L., "Automotive Mechanics" Tata McGrav any, 2004.	r gas fatigu ns. Im ure, p requi DTAL: ons an device	flow, le, dy pact erforr reme d the s ues	lates
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- 1. Rangan, Sharma and Mani, 'Instrumentation Devices and systems', Tata McGraw Hill Publishing Co., Ltd., 1990
- 2. T.G. Beckwith and Buck, 'Mechanical Measurements', Oxford and IBH Publishing House, NewDelhi, 1995
- 3. D.Patambis, 'Principle of Industrial Instrumentation', Tata McGraw Hill Publishing Co, New Delhi,1990.

COs	POs							PSOs			
COS	1	2	3	4	5	6	1	2	3		
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4	3	2	2	3	3	3	3	3	2		
5	3	2	2	3	3	3	3	3	2		
AVG	3	2	2	3	3	3	3	3	2		



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AM30	15	INTELLIGENT TRANSPORT SYSTEMS	L	Т	Ρ	С
			3	0	0	3
COUR	RSE OBJ	ECTIVES:				
	To desc	ribe the digital map database module				
2.	To desc	ribe the working of the positioning module.				
3.	To desc	ribe the working of the direction module				
		ribe the working of wireless communication module.				
j_	To desc	ribe the working of autonomous location and navigation me	odule	e.		
JNIT I		DIGITAL MAP DATABASE MODULE				Ċ,
ntrodu	uction to	Modern Vehicle Location and Navigation - Basic Represe	entat	ions -	Refe	renc
		stems – Standards - Proprietary Digital Map Databases - Dig	gital I	Мар С	compil	atior
JNIT I		POSITIONING MODULE				Ş
		ead Reckoning-Global Positioning System - Sensor fusior				
		zzy logic Based Map matching - Other Map matching alg	gorith	nms -	Мар	aide
	or calibrat					
INIT						9
		Heuristic Search - Bidirectional Search - Hierarchical sea				
		le En Route - Guidance while off Route - Guidance with d	ynan	nic inf	ormat	
NIT I						
		WIRELESS COMMUNICATION MODULE				
		Communication Subsystem Attributes - Existing Communic	catio	n Tec	hnolo	
ntrodu	uction - C	Communication Subsystem Attributes - Existing Communic n Subsystem Integration.	catio	n Tec	hnolo	
ntrodu Comm INIT V	uction - C nunicatioi V	Communication Subsystem Attributes - Existing Communic Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION				gies
ntrodu Comm JNIT V ntrodu	uction - C nunication V uction –	Communication Subsystem Attributes - Existing Communic n Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION Vehicle Location: Standalone Technologies - Radio Tec	chno	logies	s - Sa	gies
ntrodu Comm JNIT Introdu Techn	uction - (nunication V uction – nologies -	Communication Subsystem Attributes - Existing Communic n Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION Vehicle Location: Standalone Technologies - Radio Tec Vehicle Navigation: Coping with complex requirements -	chno - Dua	logies al use	s - Sa navię	gies
ntrodu Comm JNIT Introdu Techn and er	uction - (nunication V uction – nologies - ntertainm	Communication Subsystem Attributes - Existing Communic n Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION Vehicle Location: Standalone Technologies - Radio Tec Vehicle Navigation: Coping with complex requirements - ient components - Centralized location and Navigation Inter-	chno - Dua rodu	logies al use ction	s - Sa naviç - Auto	gies tellit gatio
ntrodu Comm JNIT Introdu Techn and er /ehicl	uction - C nunication V uction – nologies - ntertainm le Locatio	Communication Subsystem Attributes - Existing Communic n Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION Vehicle Location: Standalone Technologies - Radio Tec Vehicle Navigation: Coping with complex requirements -	chno - Dua rodu	logies al use ction	s - Sa naviç - Auto	gies tellit gatio
ntrodu Comm JNIT Introdu Techn and er /ehicl	uction - C nunication V uction – nologies - ntertainm le Locatio	Communication Subsystem Attributes - Existing Communic n Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION Vehicle Location: Standalone Technologies - Radio Tec Vehicle Navigation: Coping with complex requirements - ient components - Centralized location and Navigation Inter-	chno - Dua rodu	logies al use ction : Cent	s - Sa navię - Auto tralize	gies Itellit gatio mat d an
ntrodu Comm INIT Introdu Techn Ind er Vehicl Distrib	uction - C nunication V uction – nologies - ntertainm le Locatio puted.	Communication Subsystem Attributes - Existing Communic n Subsystem Integration. AUTONOMOUS LOCATION AND NAVIGATION Vehicle Location: Standalone Technologies - Radio Tec Vehicle Navigation: Coping with complex requirements - Vehicle Navigation: Coping with complex requirements - ent components - Centralized location and Navigation Intr on: Centralized and Distributed Approach- Dynamic Naviga	chno - Dua rodu	logies al use ction	s - Sa navię - Auto tralize	gies Itellit gatio mat d an
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 CO2 Apply principles of aerodynamics, including the use of spoilers, wings, and flow of devices, to optimize race car performance and cornering capabilities. CO3 Analyze and optimize race car chassis design and tuning, considering factors so weight distribution, suspension systems, and handling characteristics. CO4 Evaluate and optimize race car suspension systems to enhance stability, tractional systems in the sy	
 devices, to optimize race car performance and cornering capabilities. CO3 Analyze and optimize race car chassis design and tuning, considering factors so weight distribution, suspension systems, and handling characteristics. CO4 Evaluate and optimize race car suspension systems to enhance stability, traction 	control
weight distribution, suspension systems, and handling characteristics.CO4 Evaluate and optimize race car suspension systems to enhance stability, tractio	
CO4 Evaluate and optimize race car suspension systems to enhance stability, tractio	uch as
	n and
overall handling performance.	n, anu
CO5 Assess and optimize race car drive systems and braking systems to achieve of	optimal
performance, control, and safety on the track.	

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- 4. John Dixon, "Competition Car Composites: A Practical Handbook," Haynes Publishing, 2013.
- 5. Michael Costin and David Phipps, "Competition Car Chassis: Design, Structures, and Materials," Haynes Publishing, 2008.
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- 7. David E. Hoyle, "ISO 9000 Quality Systems Handbook: Automotive Industry Edition," Butterworth-Heinemann, 2005.
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COs				PSOs					
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	3	3	3	3	3	2
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5	3	2	2	3	3	3	3	3	2
AVG	3	2	2	3 =	3	3	3	3	2

UNIVER

PROGRESS THROUGH KNOWLEDGE

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AM3017	NOISE, VIBRATION AND HARSHNESS FOR AUTOMOBILES.	L	т	Ρ	С
		3	0	0	3
COURSE OBJ					
	and the various types of vibration with damping and withou				
	and the Various types of noise and its measurement and a	analy	sis teo	chniqu	les.
	and the various sources of noise from IC engine.				
	and the various noise controlling techniques from automot				
5. techniqu	and the various noise from mechanical components ues.	and	ıt's	supp	ressing
	FUNDAMENTALS OF ACOUSTICS AND NOISE, VIBR	RATIO	ON		9
Atmosphere, S Introduction to	nd—Predictions and Measurement, Sound Sources, Sound Sound Radiation from Structures and Their Respons Vibration, Vibration of Simple Discrete and Continuo ponse of Systems to Shock, Passive Damping	e to	Sou	nd, G	Senera
UNIT II	EFFECTS OF NOISE, BLAST, VIBRATION, AND SHO				
Impact Noise,	w-Frequency Noise, and Ultrasound on People, Auditory H Effects of Intense Noise on People and Hearing Loss,	Effec	ts of	Vibra	tion or
	s of Mechanical Shock on People, Rating Measures, De Determining Human Response to Noise.	escrip	nors,	Ontor	ia, and
Procedures for	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL	EDIC	TION	, AN I	D 9
Procedures for UNIT III Introduction to Prediction and	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRI CONTROL D Engine Noise and Vibration Sources, Internal Comb d Control—Diesel, Exhaust and Intake Noise and A	EDIC busti Acou	TION	i, ANI	D <mark>9</mark> Noise
Procedures for UNIT III Introduction to Prediction and Mufflers.	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL D Engine Noise and Vibration Sources, Internal Combined	EDIC busti Acou	TION	i, ANI	D <mark>9</mark> Noise
Procedures for UNIT III Introduction to Prediction and Mufflers. UNIT IV	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL D Engine Noise and Vibration Sources, Internal Combined Control—Diesel, Exhaust and Intake Noise and A TRANSPORTATION NOISE AND VIBRATION SOURCE PREDICTION AND CONTROL	EDIC busti Acou	on Er ustica	ngine I Des	D 9 Noise sign o
Procedures for UNIT III Introduction to Prediction and Mufflers. UNIT IV Introduction to Generation, Transmission	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL D Engine Noise and Vibration Sources, Internal Combined Control—Diesel, Exhaust and Intake Noise and A TRANSPORTATION NOISE AND VIBRATION SOURCE PREDICTION AND CONTROL to Transportation Noise and Vibration Sources, Aerodynamic Sound Sources in Vehicles—Pred and Gearbox Noise and Vibration Prediction and Combined	EDIC busti Acou ES-	on Er ustica	ngine I Des ad N	D 9 Noise sign o 9 oise-
Procedures for UNIT III Introduction to Prediction and Mufflers. UNIT IV Introduction to Generation, A Transmission Prediction and	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL D Engine Noise and Vibration Sources, Internal Combined Control—Diesel, Exhaust and Intake Noise and A TRANSPORTATION NOISE AND VIBRATION SOURCE PREDICTION AND CONTROL to Transportation Noise and Vibration Sources, Aerodynamic Sound Sources in Vehicles—Pred and Gearbox Noise and Vibration Prediction and Combined	EDIC busti Acou CES- Tire dictio Cont	e/Roan ar	ngine I Des ad N ad C Brake	D 9 Noise sign o 9 oise-
Procedures for UNIT III Introduction to Prediction and Mufflers. UNIT IV Introduction to Generation, A Transmission Prediction and UNIT V General Introd and Vibration Noise Dosime Determination Noise and Vib of Shock and	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL Dengine Noise and Vibration Sources, Internal Combined Control—Diesel, Exhaust and Intake Noise and A TRANSPORTATION NOISE AND VIBRATION SOURCE PREDICTION AND CONTROL To Transportation Noise and Vibration Sources, Aerodynamic Sound Sources in Vehicles—Pred and Gearbox Noise and Vibration Prediction and Gearbox Noise and Vibration Transducers, Measuri Measurements, Signal Acquisition, and Processing. Deters, Analyzers and Signal Generators, Equipment of Sound Power Level and Emission, Sound Intervition Data Analysis, Calibration of Measurement Micro Vibration Transducers, Metrology and Traceability of Source Prediction Complexity of Source Prediction Predictio	EDIC busti Acou ES- Tire dictio Cont S, SIC Sou for I nsity roph	e/Roa n ar rol, B SNAL quipr nd Le Data Mea ones	ngine I Des ad N ad C Brake ment, evel N Acqu asurer	D 9 Noise sign o 9 oise ontrol Noise Jeters isition ments oratior
Procedures for UNIT III Introduction to Prediction and Mufflers. UNIT IV Introduction to Generation, A Transmission Prediction and UNIT V General Introd and Vibration Noise Dosime Determination Noise and Vib	Determining Human Response to Noise. ENGINE NOISE AND VIBRATION—SOURCES, PRICONTROL Dengine Noise and Vibration Sources, Internal Comb Control—Diesel, Exhaust and Intake Noise and A TRANSPORTATION NOISE AND VIBRATION SOURCE PREDICTION AND CONTROL to Transportation Noise and Vibration Sources, Aerodynamic Sound Sources in Vehicles—Pred and Gearbox Noise and Vibration Prediction and G Control. NOISE AND VIBRATION TRANSDUCERS, ANALYSIS PROCESSING, AND MEASURING TECHNIQUES duction to Noise and Vibration Transducers, Measuri Measurements, Signal Acquisition, and Processing. eters, Analyzers and Signal Generators, Equipment of Sound Power Level and Emission, Sound Inter ration Data Analysis, Calibration of Measurement Micr Vibration Transducers, Metrology and Traceability of s.	EDIC busti Acou ES- Tire dictio Cont S, SIC Sou for I nsity roph	TION on Er istica e/Roa n ar rol, B GNAL quipr nd Le Data Mea ones, ration	ngine I Des ad N ad N ad C Brake ment, evel N Acqu asurer , Caliti and	D 9 Noise sign o g oise oise Noise Acters isition ments oration

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AM3018	PRODUCTION OF AUTOMOTIVE COMPONENTS	L	Т	Р	С
		3	0	0	3
COURSE	OBJECTIVES:	•	•	v	
	import knowledge on				
	compare and analyze the different casting process				
	design various machining process according to the requirement	nt			
	alysis of suitable process related to forming				
То	differentiate the effect of powder metallurgy on selective comp	onent	s		
5.		onon	0		
	CASTING				9
Sand cast	ing of cylinder block and liners - Centrifugal casting of flywheel	l, pisto	on ring	gs, be	aring
bushes, a	nd liners, permanent mould casting of pistons, pressure die	casti	ng of	carbu	uretor
other sma	Il auto parts. Investment casting of turbine and compressor bl	lades	of tur	bo ch	arge.
	of connecting rods - crank shafts - cam shafts - pistons - pisto				
	ont and rear axle housings - fly wheel - Honing of cylinder bore	es – C	Copy t	urning	g and
profile grii	nding machines. Melting practice of alloys.				
			<u> </u>		. 9
	onsideration of machining of various components such as f				
	ushes, and liners, permanent mould casting of pistons. 5-ax	is mil	ling to	or cor	nplex
snaped co	omponents - turbine and compressor wheels.				
UNIT III	FORGING AND EXTRUSION PROCESS				9
	aterials - process flow chart, forging of valves, connecting rod, of	rank	chaft	cam	
	shaft, transmission gear blanks, steering column. Extrusions:				
	of transmission shaft, housing spindle, steering worm blanks.				
	lydro forming - Process, hydro forming of manifold and compar				
	Hydro forming of tail lamp housing – forming of wheel disc and				
	stretch forming of auto body panels -Super plastic alloys for a				
		ACTI	~~		
UNIT IV	POWDER METALLURGY AND PROCESSING OF PL			otorio	9
	netallurgy process, process variables, Manufacture of frictio and brakes – plastics-raw material –automobile components		•		
	ion and blow – PU foam molding - Machining of plastics. Plastic				
	uring process.		ing, o	plical	parts
manulatio	PDACDECC THDAILCH KNAWLERCE				
UNIT V	RECENT TRENDS IN MANUFACTURING OF	AU	том	OBIL	E 9
	COMPONENTS				-
	njection molding - Production of aluminum MMC liners for en	•			
	ted engine blocks and valves - Recent developments in auto				
	Casting of pistons - aluminum composite brake rotors. Sinter				
	- gas injection molding of window channel – cast con process	s for a	uto pa	arts. I	Rapid
Prototypir	g Technologies: Additive manufacturing of Plastics & metals.		TOT		45
000000			TOT	AL:	45
	OUTCOMES:				
	I of the course, the student will be able to				
	ntify the methods to manufacture the vehicle components				
	alyze the requirements of each component and material				
	ferentiate between the casting and forming process				
	sign the process for manufacturing vehicle components				
CO5 Un	derstand the advanced techniques used for manufacturing Aut	tomob	ile co	mpor	ents
				Atte	sted

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- 2. Haslehurst.S.E., " Manufacturing Technology ", ELBS, London, 1990.
- 3. Rusinoff, "Forging and Forming of metals ", D.B. Taraporevala Son & Co. Pvt Ltd.,
- 4. Mumbai, 1995.
- 5. Sabroff.A.M. & Others, "Forging Materials & Processes ", Reinhold Book Corporation, New York, 1988.
- 6. Upton, "Pressure Die Casting ", Pergamon Press, 1985.
- 7. High Velocity "Forming of Metals ", ASTME, prentice Hall of India (P) Ltd., New Delhi, 1990
- 8. HMT handbook

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
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4	3	2	3	3	3	3	3	3	2
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AVG	3	2	3	3	3	3	3	3	2



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)19	REVERSE ENGINEERING IN AUTOMOBILE ENGINEERING	L	Т	Ρ	С
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		ECTIVES:				
		t knowledge on		duct	ما م م : م	
1.		ental concepts and principles of reverse engineering in	pro	aucto	desig	n and
2.	develop	and principles material characteristics, part durability and li	folim	itatio	o in ro	vorco
Ζ.		ring of product design and development.	ie iin	IIIalioi	inne	verse
3.		cept and principles of material identification and process	vorifi	cation	in re	Vorso
5.		ring of product design and development.	venn	cation		10130
4.		cept and principles of data processing, part performance and	disvs	tem c	ompa	tibility
••		se engineering of product design and development.			empe	(includy)
5.		ng the various legal aspect and applications of reverse e	naine	erina	in pi	roduct
		and development.				
UNIT		INTRODUCTION TO REVERSE ENGINEERING				12
Defini	ition – Us	es – The Generic Process – Phases – Computer Aided R	Rever	se Er	gine	ering -
Surfa	ce and So	blid Model Reconstruction – Dimensional Measurement – F				
UNIT	II	MATERIAL CHARACTERISTICS, PART DURABILI	ITY	AND	LIF	E 12
Allov	Structure	Equivalency – Phase Formation and Identification – M	echa	nical	Strer	nath –
		rt Failure Analysis - Fatigue - Creep and Stress Ruptu				
	ed Failure				•••••	
UNIT		MATERIAL IDENTIFICATION AND PROCESS VERIFIC	CATI	ON		12
Mater	ial Specif	ication - Composition Determination - Microstructure Ana	lysis	– Ma	nufac	turing
	ss Verific					U
UNIT	IV	DATA PROCESSING, PART PERFORMANCE	AND	SY	STE	M 12
		COMPATIBILITY	100			
• • • •						
		lysis – Data Analysis – Reliability and the Theory of In				
Analy	rsis – Da	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Pe				
Analy Metho	sis – Da odology o	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Pel f Performance Evaluation – System Compatibility.				eria –
Analy Metho UNIT	rsis – Da odology o V	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Per f Performance Evaluation – System Compatibility. ACCEPTANCE AND LEGALITY OF RE	rform	ance	Crite	eria – 12
Analy Metho	rsis – Da odology o V	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Pel f Performance Evaluation – System Compatibility.	rform	ance	Crite	eria – 12
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Analy Metho UNIT Legali PRAC 1. 2. 3. 4. 5. COUF	sis – Da odology o V ity of Rev CTICALS Prepare Prepare Prepare Prepare RSE OUT	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Per f Performance Evaluation – System Compatibility. ACCEPTANCE AND LEGALITY OF RE erse Engineering – Patent – Copyrights –Trade Secret – T e a function and product structure of an automotive comporend sketch of assembly and parts e part interface matrix e manufacturing drawing for assembly and parts e a prototype using 3D Printing / machining	rform <u>hird-</u> nent	Party	Crite	eria – 12 rials
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Analy Metho UNIT Legali PRAC 1. 2. 3. 4. 5. COUF Upon	sis – Da odology o V ity of Rev CTICALS Prepare Prepare Prepare Prepare RSE OUT completio Apply th and dev Apply th	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Per f Performance Evaluation – System Compatibility. ACCEPTANCE AND LEGALITY OF RE erse Engineering – Patent – Copyrights –Trade Secret – T e a function and product structure of an automotive compore nd sketch of assembly and parts e part interface matrix e manufacturing drawing for assembly and parts e a prototype using 3D Printing / machining TOTA COMES: on of this course, the students will be able to: e fundamental concepts and principles of reverse enginee elopment. e concept and principles material characteristics, part dural	rform hird- nent	Party	Crite Mate	DDS
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Analy Metho UNIT Legali PRAC 1. 2. 3. 4. 5. COUF Upon	sis – Da odology o V ity of Rev CTICALS Prepare Freehau Prepare Prepare Prepare RSE OUT completio Apply th and dev Apply th	lysis – Data Analysis – Reliability and the Theory of In ata Conformity and Acceptance – Data Report – Per f Performance Evaluation – System Compatibility. ACCEPTANCE AND LEGALITY OF RE erse Engineering – Patent – Copyrights –Trade Secret – T e a function and product structure of an automotive compore nd sketch of assembly and parts e part interface matrix e manufacturing drawing for assembly and parts e a prototype using 3D Printing / machining TOTA COMES: on of this course, the students will be able to: e fundamental concepts and principles of reverse enginee elopment. e concept and principles material characteristics, part dural se engineering of product design and development. e concept and principles of material identification and proc	rform hird- hent AL : ring i bility	Party Party n prod	Crite Mate	PDS
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CO5	Analyze the various legal aspect and applications of reverse engineering in product
	design and development.
TEXT	BOOKS:
1.	Wego Wang, "Reverse Engineering Technology of Reinvention", CRC Press, 2011.
2.	Vinesh Raj and Kiran Fernandes, "Reverse Engineering: An Industrial Perspective",
	Springer- Verlag London Limited 2008.
REFE	RENCES:
1.	Kathryn, A. Ingle, "Reverse Engineering", McGraw-Hill, 1994.
2.	Linda Wills, "Reverse Engineering", Kluver Academic Publishers, 1996
3.	Donald R. Honsa, "Co-ordinate Measurement and Reverse Engineering", American
	Gear Manufacturers Association.

COs			P	Ds				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
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3	3	2	2	2	2	2	3	3	2
4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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AM30	20	SPECIAL PURPOSE VEHICLES	L	Т	Ρ	С
			3	0	0	3
COUF	RSE OB	JECTIVES:				
1.	To enh applica	ance the knowledge of the students about the various equipment's used in itions.	n ea	rthr	novi	ng,
2.		erstand the construction and working of the vehicle for constructional ap	olica	atior	۱	
3.		cribe the working nature of farm equipment's based on their application.				
4.		criminate the various industrial vehicles based on the purpose.				
5.		uire the knowledge on the functioning of military vehicle.				
UNIT		EARTH MOVING EQUIPMENTS				9
		layout, capacity and applications of dumpers, articulated haulers, front				
		lers, bulldozers, scrappers, motor graders, skid-steer loaders, excave				
		et conveyors, surface miners- highwall Miners. Selection criteria of pr	ime	me	ver	IO
dump UNIT		CONSTRUCTIONAL EQUIPMENTS				9
		ayout, capacity and applications of cranes-types, Articulated Trucks, of	onc	rete		-
		ers, Asphalt Pavers, road reclaimers, Compactors– types, draglines, dri				
machi		, , , , , , , , , , , , , , , , , , ,		,	-	-
UNIT		FARM EQUIPMEMTS			9	9
Class	ification	of tractors - Main components of tractor. Working attachment of tract	ors	– A	uxili	ary
equipi	ment	Top lifting harvesters. General description, working, specification and fu				
		achines, Sugarcane harvesting, feller bunchers, forest machines.				
UNIT		INDUSTRIAL VEHICLES				9
		I features, capacity and working of forklifts, Utility vehicles, towing vel	nicle	es, r	nan	-lift
		or lift trucks, material handlers, reclaimers, Street sweepers.				
UNIT		MILITARYANDCOMBATVEHICLES res and constructional details of Main Battle tank, gun carriers, trans		4		9
		cle – launched bridge, amphibious bridging vehicle, communication vehi			FIIC	es,
Annoi		TOTA). 		45
COUF	RSE OU	TCOMES:	<u></u>			
		the course, the student will be able to				
CO1	Demor	strate their understanding about the operation of the various special pur	pos	e ve	hicl	e
		stand the construction layout of earthmoving equipment's.				
		ne ability to apply the knowledge to design a new concept for construction	n a	pplic	catio	on.
CO4	Demor	strate their skill in developing modern techniques for future farming vehi	cles	;		
CO5	U	uish the various military vehicles and infer their particular technology.				
	RENCE					
1.		mov.K, Branberg.A.and Katayer.K., "Road making Machinery", MIR Publ w,1971.	ishe	ers,		
2.		nev and G.Rodicheva, Tractor and Automobiles, MIR Publishers, 1987.				
3.		J.T, "Theory of Ground vehicles ", John Wiley &Sons, NewYork, 1987.				
4.		eman and M.Moskovin, "Farm tractors" ,MIR publishers, Moscow.				
5. 6.	Kolchi	Vanderveen, "Tanks and Transport vehicles", Frederic Warne and Co I n,A. and V.Demidov," Design of Automotive Engines for Tractor", MIR P				
7.		oy R.L, "Construction Planning, Equipment and Methods",Tata McGraw-	Hill,	Ne	w	
8.	Delhi,2 Wong	2002. J"Terramechanics and Off-Road Vehicle Engineering",Butterworth-Heine	ma	nn, I	200	9

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CO 2			P	Os				PSOs	
COs	1	2	3	4	5	6	1	2	3
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4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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AM30	021	THEORY OF FUELS		·s	L	Т	Р	С
	5£ 1			5	3	0	0	3
COU	RSE OBJ	CTIVES:					1 -	
1.	Tc	dentify the processes behind	fuel extraction sys	tem.				
2.		understand the theory behind						
3.		study the properties of lubrica						
4.		elaborate the properties of fue		nes.				
5.		understand the need of fuel ra						
UNIT		MANUFACTURE OF FUELS						9
polyr	merization	etroleum, refining process alkylation, isomerisation, bler se stocks, manufacture of fin	ding, products of r	efining pro				
UNIT	' II	THEORY OF LUBRICATION	N					9
hydro	dynamic	introduction, total engine brication, elasto hydrodyna ons of the lubrication system,	mic lubrication,	boundary	lubri	icatior	n, bea	aring
UNIT		PROPERTIES AND TESTIN	G OF LUBRICAN	TS				9
lubrica	ants, synt	nents for automotive lubrica etic lubricants, classification s. Grease, classification, prop	of lubricating oils	, propertie				
UNIT	IV	PROPERTIES AND TESTIN	G OF FUELS AN	D COMBU	STIO	N		9
pour coppe UNIT Add	point, flai er strip col V litive - me	oint, distillation, vapour prese mability, ignitability, diesel in <u>osion etc. combustion in SI an</u> ADDITIVES FOR LUBRICA hanism, requirements of ad echanism, for lubricants. Intro	ndex, API gravity, nd CI Engine. NTS AND FUELS ditive, petrol fuel	aniline po additives,	oint,	carbo	n resi	due, 9
				TOTAL :	45 PE	ERIOD	DS	
COU	RSE OUT	OMES: At the end of this cou	rse the student sh	ould be ab	le to			
CO1 CO2 CO3	Underst Study th	e processes behind fuel extra nd the theory behind lubrication properties of lubricants.	on UUN KAUT	LEDGE				
<u>CO4</u>		the properties of fuels used i	n IC engines.					
CO5	BOOKS	nd the need of fuel rating.						
1. 2.	Ganesan Delhi, 20 M.L. Ma publicatio	ur, R.P.Sharma "A course	in internal com	bustion er	ngine	s", Dh	nanpa	trai
REFE 1. 2. 3.	Brame, J Francis, V	C.Gunther, "Lubrication", Chil S.S. and King, J.G.,"Fuels – S ., "Fuels and Fuel Technolog Technology	olids, Liquids, Gas	eous"	& Poh		Noder	

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COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
2	3	2	2	2	2	2	3	3	2
3	3	2	2	2	2	2	3	3	2
4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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)22	TWO AND THREE WHEELERS	L	Т	Ρ	С
			3	0	0	3
COUF	RSE OBJ	ECTIVES:				
- ,						
		f this course is to make the students to				
<u>1.</u>		he knowledge on two-wheeler design and stability aspects			~ -	
2.		and the construction and working of power unit in two and the	ree-w	heele	r & Ex	pose
<u> </u>		ge on different ignition systems and electrical systems.				
<u>3.</u> 4.		weldge on clutch and transmission system of two wheelers		on tu	ia wh	
4.	-	ze various frames used in two wheelers and to gain know ion & brake systems.	leuge	ontv	vo-wn	eelei
5.		and interpret various three wheelers for different application	6			
J.			5			
UNIT		INTRODUCTION				9
		of different two wheelers based on usage - Layout of dif	ferent	t two	wheel	
		erations – weight and dimension limitations –requirement				
		ct- pendulum effect of two and three wheelers. Problems or				
UNIT		POWER UNITS, IGNITION SYSTEMS AND OTHER ELE	CTR	CAL		9
		SYSTEMS				
		four stroke engines. Single, twin and multi cylinder engines				•
		. Carburetted engines, Sensors in fuel supply system, PFI, M				
		nition, magneto ignition and electronic ignition. Lighting	and	other	elec	trical
		tion of engines for two wheelers				
UNIT		STEERING, CLUTCHES AND TRANSMISSION				9
syster Clutcł	m in two-v h- design	etry and Effects – Steering Column for Two wheelers, La wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F	oer cl	utch, (heelin	Centri g dev	fugal ⁄ices.
syster Clutch Startir drive.	m in two-v h- design ng Mecha	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives -	reew Belt,	utch, (heelin	Centri g dev	fugal ⁄ices.
syster Clutch Startin drive. UNIT	m in two-v h- design ng Mecha	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM	er clu reew Belt, (ES	utch, heelin chain	Centri g dev and	fugal rices. shaft 9
syster Clutch Startir drive. UNIT Types	m in two-v h- design ng Mecha IV s of frame	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM s. Design of frames for fatigue strength, torsional stiffness	Freew Belt, KES s and	utch, (heelin chain latera	Centri g dev and al stat	fugal rices. shaft 9 pility.
syster Clutch Startin drive. UNIT Types Front	m in two-v h- design ng Mecha IV s of frame t and rea	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM s. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Des	Freew Belt, (ES s and sign c	utch, (heelin chain latera onside	Centri g dev and al stat eration	fuga rices shaft 9 oility.
syster Clutch Startin drive. UNIT Types Front susp	m in two-v h- design ng Mecha IV s of frame t and rea ension sys	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM is. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Des stems. Constructional details of wheel and tyres. Braking sy	Freew Belt, (ES s and sign c	utch, (heelin chain latera onside	Centri g dev and al stat eration	fugal vices. shaft 9 pility. n for
syster Clutch Startin drive. UNIT Types Front susp Brake	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM s. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Des stems. Constructional details of wheel and tyres. Braking sy ock Braking system.	Freew Belt, (ES s and sign c	utch, (heelin chain latera onside	Centri g dev and al stat eration	fugal rices. shaft 9 pility. n for Disc
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM s. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Des stems. Constructional details of wheel and tyres. Braking sy ock Braking system. THREE WHEELERS	Freew Belt, KES s and sign c stems	utch, heelin chain latera onside s Drur	Centri g dev and al stat eration n and	fugal rices. shaft 9 oility. n for Disc 9
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Desistems. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, frame 	Experience of the set	utch, heelin chain latera onside s Drur	Centri g dev and al stat eration n and nsmis	fugal rices. shaft 9 oility. n for Disc 9 sion,
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Designes. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, framepension systems. Wheel types – Spoke, Pressed steel, All 	Cer clu reew Belt, (ES s and sign c stems res ar loy. T	utch, heelin chain latera onside s Drur nd tran yre –	Centri g dev and al stat eration n and nsmis Cross	fugal rices. shaft 9 oility. n for Disc 9 sion,
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Desistems. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, frame 	Cer clu reew Belt, (ES s and sign c stems res ar loy. T	utch, heelin chain latera onside s Drur nd trai	Centri g dev and al stat eration n and nsmis Cross rs	fugal rices. shaft oility. n for Disc 9 sion, and
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing Radia	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. Finisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Designers. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, frames pension systems. Wheel types – Spoke, Pressed steel, All B. Brake systems. Introduction about electric and two and the system. 	Cer clu reew Belt, (ES s and sign c stems res ar loy. T	utch, heelin chain latera onside s Drur nd trai	Centri g dev and al stat eration n and nsmis Cross	fugal rices. shaft oility. n for Disc 9 sion, and
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing Radia	m in two-v h- design ng Mecha s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus al Ply Tires RSE OUT	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. Finisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Designers. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, frames pension systems. Wheel types – Spoke, Pressed steel, All B. Brake systems. Introduction about electric and two and the system. 	Cer clu reew Belt, (ES s and sign c stems res ar loy. T	utch, heelin chain latera onside s Drur nd trai	Centri g dev and al stat eration n and nsmis Cross rs	fugal rices. shaft oility. n for Disc 9 sion, and
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syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing Radia COUF On su CO1	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus al Ply Tires RSE OUT uccessful o Demons Identify a	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. Finisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Designers. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, frame pension systems. Untroduction about electric and two and the systems. Introduction about electric and two and the systems. Introduction about electric and two and the system of this course students will be able to: 	Cer cli reew Belt, S and ign c stems rstems oy. Ty nee w	utch, heelin chain latera onside s Drur nd trai yre – <u>heele</u> TC	Centri g dev and al stat eration n and cross rs DTAL	fugal rices. shaft oility. n for Disc 9 sion, and 45
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing Radia COUF On su CO1 CO2	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus al Ply Tires RSE OUT uccessful o Demons Identify a	 wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. Finisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAMES. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Designes. Constructional details of wheel and tyres. Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, frames pension systems. Untroduction about electric and two and the systems. Introduction about electric and two and the systems. COMES: completion of this course students will be able to: trate and design the two-wheeler and stability. and distinguish various two-wheeler power unit functions and trate various design aspects of clutch and transmission systems. 	Cer cli reew Belt, S and ign c stems rstems oy. Ty nee w	utch, heelin chain latera onside s Drur nd trai yre – <u>heele</u> TC	Centri g dev and al stat eration n and cross rs DTAL	fugal rices shaft oility. n for Disc 9 sion, and 45
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing Radia COUF On su CO1 CO2 CO3	m in two-v h- design ng Mecha ing Mecha s of frame t and rea ension systems. Anti Lo v s. Anti Lo v rickshaws g arm sus al Ply Tires RSE OUT uccessful of Demons Identify a wheelers	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM s. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Des stems. Constructional details of wheel and tyres. Braking sy ock Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, fram pension systems. Wheel types – Spoke, Pressed steel, All s. Brake systems. Introduction about electric and two and th COMES: completion of this course students will be able to: trate and design the two-wheeler and stability. and distinguish various two-wheeler power unit functions an trate various design aspects of clutch and transmission sys and identify the different two wheelers frames and its sub	CES S and Sign C Stems Nes ar Nes ar Nov. Ty nee w	utch, heelin chain latera onside s Drur nd tran yre – <u>theele</u> TC	Centri g dev and al stat eration n and Cross rs DTAL	fuga rices shaft pility. n for Disc 9 sion, and 45 is three
syster Clutch Startin drive. UNIT Types Front susp Brake UNIT Auto Swing Radia	m in two-v h- design ng Mecha IV s of frame t and rea ension sys es. Anti Lo V rickshaws g arm sus al Ply Tires RSE OUT uccessful of Demons Identify a Describe applicati	wheeler. Clutch - Single and multi plate clutch, Assist Slipp of clutch. Gear boxes. Gear change mechanism. CVT. F nisms – Kick & Electrical start mechanism. Final drives - FRAMES, SUSPENSION, WHEELS, TYRES AND BRAM s. Design of frames for fatigue strength, torsional stiffness r forks. Telescopic Suspension system - Dampers, Des stems. Constructional details of wheel and tyres. Braking sy bok Braking system. THREE WHEELERS , different types, Pick-Ups and delivery type vehicle, fram pension systems. Wheel types – Spoke, Pressed steel, All s. Brake systems. Introduction about electric and two and th COMES: completion of this course students will be able to: trate and design the two-wheeler and stability. and distinguish various two-wheeler power unit functions an trate various design aspects of clutch and transmission sys e and identify the different two wheelers frames and its sub ons and distinguish the different three wheelers and its sub	A light A l	utch, heelin chain latera onside s Drur nd trai yre – heele TC	Centri g dev and al state eration n and msmis Cross rs DTAL ystem o and t	fugal rices shaft oility. n for Disc 9 sion, and 45 three erent

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TEXT BOOKS:

- 1. Edward Abdo, Modern motor cycle technology by 3rd Edition, 2015
- 2. Irving, P.E., Motor cycle Engineering, Temple Press Book, London, 1992.

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- 1. K. K. Ramalingam, Two Wheelers, Scitech publications, Chennai
- 2. Motorcycle Basics Tech book by Haynes 2nd Edition, 2015
- 3. Motorcycle mechanics, By George Lear, 1977
- 4. Motorcycle Owner's Manual By Hugo Wilson 1997
- 5. The Essential Guide to Motorcycle Maintenance By Mark Zimmerman2016
- 3. Two and Three Wheeler Technology, Dhruv U.Panchal, PHI Learning, 2015

COs			P	Os				PSOs	
COS	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
2	3	2	2	2	2	2	3	3	2
3	3	2	2	2	2	2	3	3	2
4	3	2	2	2	2	2	3	3	2
5	3	2	2	2	2	2	3	3	2
AVG	3	2	2	2	2	2	3	3	2



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COURSE OBJECTIVES: The objective of this course is to make the students to 1. To solve the simple problems related to psychrometry and refrigerant. 2. To understand the operation of the individual components of the A/System, sensors, actuators and electronic control. 3. To understand the range of techniques that can be used in diagnosing 4. To identify faults which affect system performance. 5. To provide adequate knowledge in safe working practice. Understanding the correct procedures for A/C service and repair. UNIT I AUTOMOTIVE AIRCONDITIONING FUNDAMENTALS 9 9 Purposes of Heating, Ventilation and Air Conditioning. Environmental Concerns- Ozone laye depletion. Location of air conditioning components in a car – Schematic layout of a vehicle refrigeration system. Psychrometry – Basic terminology and Psychrometric Mixtures Psychrometric Chart. Related problems. 9 Vehicle Refrigeration System and related problems. Fixed thermostatic and Orifice tube system Variable displacement thermostatic and Orifice tube system- Vehicle air conditioning operatio Types of control devices- Preventing Compressor Clutch electrical circuit. Compressor lubrication- Condensers. Evaporators - Expansion devices. Foxporator temperature and pressure controls - Receiver-drier - Accumulators - refrigeration system diagnosis – Diagnosti procedure- Ambient conditions affecting system. 9 MINI III AUTOMOTIVE COULING CONTROLS, DELIVERY SYSTEM AND System.	AM3023	VEHICLE AIR CONDITIONING SYSTEMS		Т	Ρ	С	
The objective of this course is to make the students to 1 To solve the simple problems related to psychrometry and refrigerant. 2. To understand the operation of the individual components of the A/System, sensors, actuators and electronic control. 3. To understand the range of techniques that can be used in diagnosing 4. To identify faults which affect system performance. 5. To provide adequate knowledge in safe working practice. Understanding the correct procedures for A/C service and repair. UNIT I AUTOMOTIVE AIRCONDITIONING FUNDAMENTALS 9 Purposes of Heating, Ventilation and Air Conditioning: Environmental Concerns- Ozone laye depletion. Location of air conditioning components in a car - Schematic layout of a vehicle refrigeration system. Psychrometry – Basic terminology and Psychrometric Mixtures Psychrometric Chart: Related problems. 9 VINT II AUTOMOTIVE COLING AND HEATING SYSTEM 9 9 Vehicle Refrigeration System and related problems- Fixed thermostatic and Orifice tube system Variable displacement thermostatic and Orifice tube system. 9 Variable displacement thermostatic Compressor Clutches - Compressor Clutch electrical circuit. Compressor Lutch electrical circuit. Compr				0	0	3	
1. To solve the simple problems related to psychrometry and refrigerant. 2. To understand the operation of the individual components of the A/System, sensors, actuators and electronic control. 3. To understand the range of techniques that can be used in diagnosing 4. To identify faults which affect system performance. 5. To provide adequate knowledge in safe working practice. Understanding the correct procedures for A/C service and repair. UNIT I AUTOMOTIVE AIRCONDITIONING FUNDAMENTALS 9 9. Purposes of Heating, Ventilation and Air Conditioning - Environmental Concerns- Ozone laye depletion - Location of air conditioning components in a car – Schematic layout of a vehicle refrigeration system. Psychrometry – Basic terminology and Psychrometric Mixtures Psychrometric Chart. Related problems. UNIT II AUTOMOTIVE COOLING AND HEATING SYSTEM 9 Vehicle Refrigeration System and related problems. Fixed thermostatic and Orifice tube system Variable displacement thermostatic and Orific tube system. Variable displacement thermostatic and Orifice tube system. <td colsp<="" th=""><th>COURSE OBJ</th><th>ECTIVES:</th><th></th><th></th><th></th><th></th></td>	<th>COURSE OBJ</th> <th>ECTIVES:</th> <th></th> <th></th> <th></th> <th></th>	COURSE OBJ	ECTIVES:				
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- 2. McDonald, K.L., Automotive Air Conditioning, Theodore Audel series, 1978.
- 3. Mitchell Information Services, Inc., Mitchell Automatic Heating and Air Conditioning Systems, Prentice Hall Inc., 1989.
- 4. Paul Weisler, Automotive Air Conditioning, Reston Publishing Co. Inc., 1990

C O2			P	Os				PSOs	
COs	1	2	3	4	5	6	1	2	3
1	3	2	2	2	2	2	3	3	2
2	3	2	2	2	2	2	3	3	2
3	3	2	2	2	2	2	3	3	2
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AVG	3	2	2	2	2	2	3	3	2



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AM3024		VEHICLE EMBEDDED SYSTEMS	L	T	Ρ	С					
COURSE OBJ			3	0	0	3					
1.		ECTIVES: use the students to the fundamentals and building of Eleventers	ctroni		ino C	ontrol					
••	systems	•	CUOIN	5 Eng		Unition					
2.		To teach on functional components and circuits for vehicles.									
3.		iss on programmable controllers for vehicles managemen	nt svs	tems.							
4.		n logics of automation & commercial techniques for vehic			icatio	n.					
5.		duce the embedded systems concepts for E-vehicle systemeters									
UNIT I BASIC OF ELECTRONIC ENGINE CONTROL SYSTEMS 9											
perfor select for Er SAE-	mance; ion and r ngine Ma	utomotive systems, fuel economy, air-fuel ratio, emiss Automotive microcontrollers- Electronic control Unit- I equirements for Automotive applications – open source E nagement-Standards; Introduction to AUTOSAR and In nal safety ISO 26262- Simulation and modelling o	Hardw ECU- ntrodu	are RTOS	& sof 6 - Co to S	ftware oncept ociety					
UNIT		SENSORS AND ACTUATORS FOR AUTOMOTIVES				9					
senso	r and act	ors- sensors interface to the ECU, conventional sensors uators - LIDAR sensor- smart sensors- MEMS/NEMS ser plications.									
UNIT		VEHICLE MANAGEMENT SYSTEMS				9					
contro electro electri assiste UNIT On bo Vehicl recent	ol, electro onic susp le system c vehicle ed power IV pard diag le comm t trends ir	ine Control-engine mapping, air/fuel ratio spark timing nic ignition- Adaptive cruise control - speed control-anti-lo- bension - electronic steering, Automatic wiper control- n schematic for interfacing with EMS, ECU. Energy Ma es- Battery management system, power management steering system- Adaptive lighting system- Safety and C ONBOARD DIAGONSTICS AND TELEMATICS nosis of vehicles -System diagnostic standards and re unication protocols Bluetooth, CAN, LIN, FLEXRAY, M n vehicle communications- Navigation- Connected Cars t	ocking body anage ent sy collisio gulati 40ST echno	braki cont ment vstem n Avc on re , KW	ng sy rol sy syste -elect bidanc quirer P2000 – Tra	rstem- rstem; em for rically ce. 9 ments 0 and cking-					
		ta communication- dashboard display and Virtual Instru	menta	ation,	multir	media					
UNIT		le of IOT in Automotive systems ELECTRIC VEHICLES				9					
Electri	ic vehicle	s –Components- Plug in Electrical vehicle- Charging statio	on – A	ggreg	gators						
00:		TOTAL:	45 PE	RIOD)S						
		COMES:	.4	4		41					
CO1		nto the significance of the role of embedded system for au				IIIONS.					
CO2 CO3		e the need, selection of sensors and actuators and interfa the Embedded concepts for vehicle management and co									
CO3	Demons	strate the need of Electrical vehicle and able to apply t	he en	nbedr	ins. led s	vstem					
		bgy for various aspects of EVs				,					
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design and its application in automotive system										
REEE	RENCES										
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2.	Jack Er	Jack Erjavec, Jeff Arias, "Alternate Fuel Technology-Electric, Hybrid& Fuel Cell Vehicles", Cengage ,2012.									
3.	Edition,	Tom Denton, Automotive Electricals / Electronics System and Components, 3 rd Edition, 2004.									
4. 5	Robert Bosch Gmbh, Automotive Electricals Electronics System and Components, 4 th Edition,2004.										
5.		di, Mehrdedehsani, John M Miller, "Vehicular Electric pov Space Vehicles" Marcel Decker, 2004.	wer sy	stem	land	, Sea,					

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- 6. L.Vlacic, M. Parent, F. Harahima," Intelligent Vehicle Technologies", SAE International,2001.
- 7. Chilton Automotive Books, Electronic Engine Control technology Ronald K Jurgen Chilton's guide to Fuel Injection Ford, W G Nichols Publishers, 1991
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- 9. Robert Bosch, Automotive Hand Book, Bently Publishers, 1997.
- 10. Jurgen, R., Automotive Electronics Hand Book

COs	POs						PSOs			
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5	3	3	3	3	3	3	3	3	2	
AVG	3	3	3	3	3	3	3	3	2	



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